

复数方法

§1.1 复数及运算

1. 起源

$$x^2 + ax + b = 0$$

$$x = b - \frac{a}{2}$$

$$t^2 + pt + q = 0$$

$$t = u + v$$

$$u^3 + v^3 + (u+v)(3uv) + p(u+v) + q = 0$$

$$\text{Assume } 3uv + p = 0$$

$$\begin{cases} u^3 + v^3 + q = 0 \\ uv = -\frac{p}{3} \end{cases}$$

$$u^3 + v^3 + q = 0$$

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$$\begin{cases} u = \sqrt[3]{\frac{-q + \sqrt{q^2 + \frac{4}{27}p^3}}{2}} \\ v = -\frac{p}{3u} \end{cases} \Rightarrow x = u + v - \frac{p}{3}$$

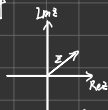
2. 定义 同群

$$\textcircled{1} z = x + iy$$

$$\textcircled{2} 三角表达$$

$$\textcircled{3} 极坐标 \quad z = e^{i\varphi} \quad \arg z = \varphi + 2\pi k$$

$$\textcircled{4} \text{例} \quad \text{电投影}$$



3. 表示

4. 复共轭

5. 运算规则

$$z = x + iy$$

$$x = \operatorname{Re} z$$

$$y = \operatorname{Im} z$$

$$z = \rho e^{i\varphi}$$

例: 求根

$$\textcircled{1} \sqrt[n]{a+ib} = C + iD$$

$$\textcircled{2} z = a+ib = \rho e^{i\varphi}$$

$$= \sqrt[n]{a^2+b^2} e^{i\frac{\varphi}{n}}$$

$$= (a^2+b^2)^{\frac{1}{2n}} e^{i\frac{\varphi}{n}}$$

$$= (a^2+b^2)^{\frac{1}{2n}} \left[\cos \frac{1}{n} \arctan \frac{b}{a} + i \sin \frac{1}{n} \arctan \frac{b}{a} \right]$$

$$x \in \mathbb{R}, \quad |\cos x| \leq 1$$

$$z \in \mathbb{C}, \quad |\cos z| \text{ 可能} > 1$$

$$\cos i = \frac{e^{-1} + e^1}{2} > 1$$

$$\Downarrow$$

$$\cos ia = \frac{e^{-a} + e^a}{2} = \cosh a$$

$$\sin(ib) = \frac{e^b - e^{-b}}{2i} = \frac{e^b - e^{-b}}{2} i = i \sinh b$$

$$\cosh ia = \cos a$$

$$\sinh ib = \sin b$$

§1.2 复变函数

$$x \mapsto z = x + iy$$

$$f(z) = u(x, y) + i v(x, y)$$

Def: 如果复数 z 在复平面或复球面上的某区域 B 上连续变化, 若复变数 w 的值随着 z 值而变化

则称 $w = f(z)$ 为 B 上的复变函数. 记为 $w = f(z)$, $z \in B$

例: 1) $D_c(z) = \{z \mid |z-1| < \frac{1}{2}\}$ z 的邻域

或: 2) 一定有邻域的内点组成

3) 具有连通性, 即点集中任意两点都可以用折线连接.

3) 即: ① 复数式: $w = f(z) = C_0 + C_1 z + C_2 z^2 + C_3 z^3 = u(x, y) + i v(x, y)$ C_i 复常数

② 有理式: $w = f(z) = \frac{C_0 + C_1 z + C_2 z^2 + \dots + C_n z^n}{b_0 + b_1 z + b_2 z^2 + \dots + b_m z^m}$

③ 根式: $\sqrt[n]{z - z_0} \Rightarrow$ 多值函数 $z - z_0 \xrightarrow{\text{开方}} \begin{cases} \sqrt[n]{z - z_0} \\ \sqrt[n]{z - z_0} e^{i\frac{2\pi}{n}} \\ \sqrt[n]{z - z_0} e^{i\frac{4\pi}{n}} \end{cases}$

④ 初等函数

$h z = \rho z + i 2 k \pi = \rho e^{i\theta} + i 2 k \pi$

$e^z = e^{x+iy} = e^x \cdot e^{iy} = e^x \cos y + i e^x \sin y$

$\sin z = \frac{e^{iz} - e^{-iz}}{2i} = \frac{1}{2} \left[\frac{e^{i(x+iy)} - e^{-i(x+iy)}}{2} \right] = \frac{1}{2} (i \cos x - \sin x) e^{-y} = \sin x \cosh y + i \cos x \sinh y \quad \sim \sin(x+iy)$

$\cos z = \frac{e^{iz} + e^{-iz}}{2} = \frac{1}{2} (e^{i(x+iy)} + e^{-i(x+iy)}) = \frac{1}{2} (\cos x - i \sin x) e^{-y} = \cos x \cosh y - i \sin x \sinh y \quad \sim \cos(x+iy)$

$e^z, \sin z, \cos z$ 均有复周期.

§1.3 复导数

1) Def: $\frac{df(z)}{dz} = \lim_{\Delta z \rightarrow 0} \frac{f(z+\Delta z) - f(z)}{\Delta z}$

2) 必要条件的: $f'(z) = \lim_{\Delta z \rightarrow 0} \frac{f(z+\Delta z) - f(z)}{\Delta z} = \lim_{\substack{\Delta x \rightarrow 0 \\ \Delta y \rightarrow 0}} \frac{f(z+\Delta x + i\Delta y) - f(z)}{\Delta x + i\Delta y} = \lim_{\substack{\Delta x \rightarrow 0 \\ \Delta y \rightarrow 0}} \frac{f(z+\Delta x) - f(z)}{\Delta x} = \lim_{\Delta x \rightarrow 0} \frac{f(z+i\Delta y) - f(z)}{i\Delta y}$

$\lim_{\substack{\Delta x \rightarrow 0 \\ \Delta y \rightarrow 0}} \frac{u(x+\Delta x, y) + i v(x+\Delta x, y) - u(x, y) - i v(x, y)}{\Delta x + i\Delta y} = \frac{\partial u}{\partial x} + i \frac{\partial v}{\partial x} = \lim_{\substack{\Delta x \rightarrow 0 \\ \Delta y \rightarrow 0}} \frac{u(x, y+\Delta y) + i v(x, y+\Delta y) - u(x, y) - i v(x, y)}{i\Delta y} = -i \frac{\partial u}{\partial y} + \frac{\partial v}{\partial y}$

等价于	$\frac{\partial f}{\partial \bar{z}} = \frac{\partial f}{\partial \bar{z}} = 0$
	or
	$\frac{\partial f}{\partial \bar{z}^2} = 0$

3) 充分条件

u, v, u_x, v_x, u_y, v_y 连续 - 且满足柯西-黎曼条件

$\Rightarrow \begin{cases} \frac{\partial u}{\partial x} = \frac{\partial v}{\partial y} \\ \frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x} \end{cases}$

4) 极坐标下的柯西-黎曼条件

$u(x, y) = u(\rho, \theta)$

$\frac{\partial u}{\partial x} = \frac{\partial u}{\partial \rho} \frac{\partial \rho}{\partial x} + \frac{\partial u}{\partial \theta} \frac{\partial \theta}{\partial x} \quad \begin{cases} \frac{\partial \rho}{\partial x} = \frac{x}{\rho} = \cos \theta \\ \frac{\partial \theta}{\partial x} = -\frac{1}{\rho \sin \theta} \end{cases}$

$\frac{\partial u}{\partial y} = \frac{\partial u}{\partial \rho} \frac{\partial \rho}{\partial y} + \frac{\partial u}{\partial \theta} \frac{\partial \theta}{\partial y}$

$\frac{\partial u}{\partial x} = \frac{\partial u}{\partial \rho} \frac{\partial \rho}{\partial x} + \frac{\partial u}{\partial \theta} \frac{\partial \theta}{\partial x}$
 $\frac{\partial v}{\partial x} = \frac{\partial v}{\partial \rho} \frac{\partial \rho}{\partial x} + \frac{\partial v}{\partial \theta} \frac{\partial \theta}{\partial x}$

$\lim_{\substack{\Delta \rho \rightarrow 0 \\ \Delta \theta \rightarrow 0}} \frac{u(\rho+\Delta \rho, \theta) - u(\rho, \theta) + i v(\rho+\Delta \rho, \theta) - i v(\rho, \theta)}{\Delta \rho e^{i\theta}}$

$= \lim_{\substack{\Delta \rho \rightarrow 0 \\ \Delta \theta \rightarrow 0}} \frac{u_\rho \Delta \rho + i v_\rho \Delta \rho + u_\theta \Delta \theta + i v_\theta \Delta \theta}{i \Delta \rho e^{i\theta}}$

$= \lim_{\Delta z \rightarrow 0} \frac{\Delta f(z)}{\Delta z} = \frac{df(z)}{dz}$

$= \frac{\partial u}{\partial \rho} e^{-i\theta} + i \frac{\partial v}{\partial \rho} e^{-i\theta} = \frac{\partial u}{\partial \rho} e^{-i\theta} + \frac{1}{\rho} \frac{\partial v}{\partial \theta} e^{-i\theta}$

$\Rightarrow \begin{cases} \frac{\partial u}{\partial \rho} = \frac{1}{\rho} \frac{\partial v}{\partial \theta} \\ \frac{\partial v}{\partial \rho} = -\frac{1}{\rho} \frac{\partial u}{\partial \theta} \end{cases}$

§1.4 解析函数

1) 定义 ① $f(z)$ 在 $z \in B$ 中, $z = z_0$ 即邻域内处处有, 称 $f(z)$ 在 z_0 处解析

② 若在区域 B 上每点解析, 则称 $f(z)$ 在 B 上解析

2) 性质:

① 在解析区域内每以线系每 ν 线' 相互正交 $\nabla u \cdot \nabla v = 0$ $(\frac{\partial u}{\partial x} \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \frac{\partial v}{\partial y}) = 0$
 $(u(x,y) = C_1) (v(x,y) = C_2)$

② 实部 u 和虚部 v 均为调和函数

即 $\Delta u = 0 \quad \Delta v = 0$

$$\Rightarrow \begin{cases} \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0 \\ \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} = 0 \end{cases}$$

or

$$\begin{cases} u_{xx} + u_{yy} = 0 \\ v_{xx} + v_{yy} = 0 \end{cases}$$

$$\nabla = \vec{e}_x \frac{\partial}{\partial x} + \vec{e}_y \frac{\partial}{\partial y}$$

$$\nabla = \vec{e}_x \frac{\partial}{\partial x} + \vec{e}_y \frac{\partial}{\partial y} \Rightarrow \nabla \cdot \nabla = \frac{\partial^2}{\partial x^2} + \frac{\vec{e}_y \cdot \frac{\partial \vec{e}_x}{\partial y}}{\cancel{\frac{\partial}{\partial x}}} + \frac{\vec{e}_y \cdot \frac{\partial \vec{e}_y}{\partial y}}{\cancel{\frac{\partial}{\partial y}}} + \frac{1}{\cancel{r^2}} \frac{\partial^2}{\partial y^2}$$

$$\frac{\partial \vec{e}_x}{\partial y} = \lim_{\Delta y \rightarrow 0} \frac{\vec{e}_x(y+\Delta y) - \vec{e}_x(y)}{\Delta y} = \vec{e}_y = \frac{\partial}{\partial y}$$

$$\frac{\partial \vec{e}_y}{\partial y} = \lim_{\Delta y \rightarrow 0} \frac{\vec{e}_y(y+\Delta y) - \vec{e}_y(y)}{\Delta y} = -\vec{e}_x$$

③ $f(z)$ 为解析函数

已知 u 求 $v \rightarrow dv = \frac{\partial v}{\partial x} dx + \frac{\partial v}{\partial y} dy = -\frac{\partial u}{\partial y} dx + \frac{\partial u}{\partial x} dy$

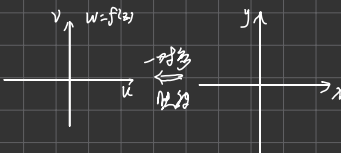
已知 v 求 u

$$v(x,y) = \int dv \quad \begin{cases} ① \text{ 曲线积分} \\ ② \text{ 全微分} \\ ③ \text{ 不定积分} \end{cases}$$

§1.5 平面标量场

$$f(z) = z^k \text{ 非解析函数}$$

§1.6 多值函数



1) 支点

$z=0$ 为 $\sqrt{z}$ 的一阶支点

$z=0$ 为 $\sqrt[3]{z}$ 的二阶支点

$z=0$ 为 $\ln z$ 的无穷阶支点

对 $\sqrt{z-a}$, $z=a$ 为一阶支点, $z=\infty$ 也为支点

对 $\sqrt{z-a} \sqrt{z-b}$, $z=a, z=b$ 均为支点

$\sqrt[n]{(z-a)(z-b)(z-c)}$, $z=a, z=b, z=c$ 为支点

$\sqrt[n]{(z-a)(z-b)(z-c)}$, $z=a, z=b, z=c, z=\infty$ 为支点

2) 黎曼面 Riemann Surface

将多值函数单值化

补充:

$$f = \frac{1}{2}(z + \bar{z})$$

$$\frac{\partial f}{\partial z} = \frac{\partial}{\partial z} \frac{z + \bar{z}}{2} = \frac{1}{2} \frac{\partial (u+iv)}{\partial z} = \frac{1}{2} \left(\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} \right) + \frac{i}{2} \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)$$

$$\frac{\partial f}{\partial \bar{z}} = \frac{\partial}{\partial \bar{z}} \frac{z + \bar{z}}{2} = \frac{1}{2} \frac{\partial (u+iv)}{\partial \bar{z}} = \frac{1}{2} \left(\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) - \frac{i}{2} \left(\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right)$$

§2 复变函数积分

§2.1 复变函数积分

在平面上分段光滑的曲线上定义的连续函数 $f(z)$

沿从 A 到 B 的路径积分:

$$\int_L f(z) dz = \lim_{n \rightarrow \infty} \sum_{k=1}^n f(z_k) \Delta z_k$$

解析函数，积分与路径无关。



非解析函数，积分或为路径有关。

$$\int_L f(z) dz = \int_L [u(x,y) + i v(x,y)] [dx + i dy]$$

$$= \int_L u dx - v dy + i \int_L v dx + u dy$$

§2.2 柯西定理

1) 若 $f(z)$ 为单连通区域上的解析函数，则 $\oint_L f(z) dz = 0$

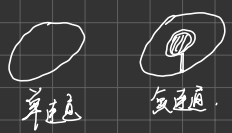
$$\oint_L f(z) dz = \oint_L u dx - v dy + i \oint_L u dy + v dx$$

Green:

$$-\iint_D \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) dx dy + i \iint_D \left(\frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} \right) dx dy$$

Stokes:

$$\oint_L E \cdot d\vec{s} = \iint_D (\nabla \times E) \cdot d\vec{s}$$



§2.3 不定积分

若 $f(z)$ 在 D 上解析 $\Rightarrow F(z) = \int_{z_0}^z f(z) dz \Rightarrow F(z)$ 在 D 上解析，且 $F'(z) = f(z)$

$$\lim_{\Delta z \rightarrow 0} \frac{F(z+\Delta z) - F(z)}{\Delta z} = \lim_{\Delta z \rightarrow 0} \frac{\int_z^{z+\Delta z} f(z) dz}{\Delta z} = f(z)$$

$$I = \oint_L (z-a)^n dz$$

① a 不在 L 内 $I=0$

② a 在 L 内, $\begin{cases} 1) n \geq 0 \\ 2) n < 0 \end{cases} \quad I=0$



$$I = 0 + \oint_C (ze^{iy})^n d(a + se^{iy})$$

$$= \int_0^{2\pi} a^n e^{iny} se^{iy} dy$$

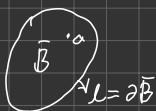
$$= i \int_0^{2\pi} a^n e^{i(n+1)y} dy \quad \underline{n=-1} \quad \underline{i \int_0^{2\pi} dy = 2\pi i}$$

$$\underline{\frac{n+1}{n+1}} \cdot i \cdot \frac{1}{i(n+1)} \cdot a^{n+1} (e^{i(n+1)2\pi} - 1)$$

$$= \underline{\frac{a^{n+1}}{(n+1)} [e^{i(n+1)2\pi} - 1]} = 0$$

§ 1.4 柯西公式

$$f(a) = \frac{1}{2\pi i} \oint_L \frac{f(z)}{z-a} dz$$



$$f(a) = \frac{1}{2\pi i} \oint_{C_3} \frac{f(z)}{z-a} dz = \frac{f(a)}{2\pi i} \int_{C_3} \frac{1}{z-a} dz$$



$$f'(a) = \frac{1}{2\pi i} \oint_L \frac{f(z)}{(z-a)^2} dz$$

$$f''(a) = \frac{1}{2\pi i} \oint_L \frac{f(z)}{(z-a)^3} dz$$

$$f'''(a) = \frac{1}{2\pi i} \oint_L \frac{f(z)}{(z-a)^4} dz$$

⋮

$$f^{(n)}(a) = \frac{n!}{2\pi i} \oint_L \frac{f(z)}{(z-a)^{n+1}} dz$$

模数原理: $f(z)$ 在 $\bar{B}$ 解析, 则 $|f(z)|_{\max}$ 在边界 L 上取得

$$|f(z)|^n = \frac{1}{2\pi i} \oint_L \frac{[f(z)]^n}{z-a} dz \leq \frac{1}{2\pi} \frac{M^n}{\delta}$$

$$|f(z)| \leq M \left(\frac{\delta}{2\pi\delta} \right)^{\frac{1}{n}} \leq M$$

如 $|f(z)|$ 在 L 上的极大值为 M , $|z-a|$ 的极小值为 δ , L 的长为 s

§3 幂级数展开

§3.1 复项幂级数

$$\sum_{n=0}^{\infty} w_n = \sum_{n=0}^{\infty} u_n + i \sum_{n=0}^{\infty} v_n$$

$$\sum_{n=0}^{\infty} w_n \text{ 收敛} \iff \begin{cases} \sum_{n=0}^{\infty} u_n \\ \sum_{n=0}^{\infty} v_n \end{cases} \text{ 收敛}$$

柯西收敛判据

$$\exists M, \forall \varepsilon > 0, \forall n > N, \forall p \in \mathbb{N}, \left| \sum_{k=n+1}^{n+p} w_k \right| < \varepsilon \iff \sum_{n=0}^{\infty} w_n \text{ 收敛}$$

$$\sum_{n=0}^{\infty} |w_n| = \sum_{n=0}^{\infty} \sqrt{u_n^2 + v_n^2} \text{ 收敛} \implies \sum_{n=0}^{\infty} w_n \text{ 绝对收敛} \implies \sum_{n=0}^{\infty} w_n \text{ 收敛}$$

函数项级数: $\sum_{n=0}^{\infty} w_n(z)$ 若在 B 上所有点, $\sum_{n=0}^{\infty} w_n(z)$ 都收敛, 则 $\sum_{n=0}^{\infty} w_n(z)$ 在 B 上收敛

充要条件: $\exists N \in \mathbb{N}, \forall n > N, \forall p \in \mathbb{N}, n > N, z \in B, \left| \sum_{k=n+1}^{n+p} w_k(z) \right| < \varepsilon$

若 $\forall \varepsilon > 0, \exists N \in \mathbb{N}, \forall n > N, \forall z \in B, \left| \sum_{k=1}^n w_k(z) - w(z) \right| < \varepsilon \implies \sum_{k=0}^{\infty} w_k(z) \xrightarrow{B} w(z)$

B 上一致收敛级数每一项 $w_k(z)$ 在 B 上连续, 级数和 $w(z)$ 在 B 上连续

若 B 为曲线, 则级数可设 $\int$ 逐项积分

$$\int_B w(z) dz = \int_B \sum_{n=0}^{\infty} w_n(z) dz = \sum_{n=0}^{\infty} \int_B w_n(z) dz$$

若 B 上级数 $\sum_{n=0}^{\infty} w_n(z)$ 一致收敛, $w_k(z)$ 在 B 上单值解析, 则 $w(z)$ 也为 B 中单值解析函数

可逐项求导: $w^{(n)}(z) = \sum_{k=0}^{\infty} w_k^{(n)}(z)$

在 B 内任意一个闭区域中一致收敛

若对 B 上各点 z , $|w_k(z)| \leq m_k$, 且 $\sum_{k=0}^{\infty} m_k$ 收敛, 则 $\sum_{k=0}^{\infty} w_k(z)$ 在 B 上一致收敛

§3.2 幂级数 (Power Series)

def $\sum_{k=0}^{\infty} a_k(z-z_0)^k = a_0 + a_1(z-z_0) + a_2(z-z_0)^2 + \dots$

a_k, z_0 均为复常数

$$\begin{cases} \lim_{k \rightarrow \infty} \left| \frac{a_{k+1}}{a_k} \right| |z-z_0| < 1 & \text{绝对收敛} \\ \lim_{k \rightarrow \infty} \left| \frac{a_{k+1}}{a_k} \right| |z-z_0| > 1 & \text{发散} \end{cases}$$

$$\begin{cases} \lim_{k \rightarrow \infty} \sqrt[k]{|a_k|} |z-z_0| < 1 & \text{绝对收敛} \\ \lim_{k \rightarrow \infty} \sqrt[k]{|a_k|} |z-z_0| > 1 & \text{发散} \end{cases}$$

$$R = \lim_{k \rightarrow \infty} \left| \frac{a_k}{a_{k+1}} \right| = \lim_{k \rightarrow \infty} \frac{1}{\sqrt[k]{|a_k|}}$$

收敛半径

① $\sum_{n=0}^{\infty} a_n(z-z_0)^n$ 在收敛圆内部绝对一致收敛

② $\sum_{n=0}^{\infty} a_n(z-z_0)^n$ 可沿收敛圆内部一周周 C_R 上逐项积分

$$\frac{1}{2\pi i} \oint_{C_R} \frac{w(z)}{s-z} dz = a_0 + a_1(z-z_0) + \dots$$

可求得任意多项
为解析函数

③ $w(z)$ 在收敛圆内为解析函数, 不可能出现奇点

④ 求导或积分不改变收敛半径

§3.3 Taylor 级数展开

($R_1 < R_2$)

$f(z)$ 在以 z_0 为中心的 C_R 内解析, 则 $f(z) = \sum_{n=0}^{\infty} a_n(z-z_0)^n$, $a_n = \frac{1}{2\pi i} \oint_{C_R} \frac{f(\zeta)}{(\zeta-z_0)^{n+1}} d\zeta = \frac{f^{(n)}(z_0)}{n!}$
唯一- R_2

§3.4 解析延拓

def. 将 $f(z)$ 区域从 A 扩展到 B , 找到 $f(z)$ 在 B 上解析. 在 $b \in B$ 上 $F(z) = f(z)$
解析延拓是唯一的

验证: 假设 $G(z) \equiv f(z) - f(z)$ 存在奇点. 证伪



§3.5 洛朗级数展开 (Laurent's Power Series)

def. 可含负幂次项的幂级数展开
除去可去奇点上的环域的展开

定理: $f(z)$ 在环域 $R_1 < |z-z_0| < R_2$ 的内部单值解析

$$\text{则 } f(z) = \sum_{k=-\infty}^{+\infty} a_k(z-z_0)^k, \quad a_k = \frac{1}{2\pi i} \oint_C \frac{f(\zeta)}{(\zeta-z_0)^{k+1}} d\zeta \neq \frac{f^{(k)}(z_0)}{k!} \quad \text{多值呢!}$$

$z=z_0$ 在实轴上为洛朗级数的奇点时, 不一定为原级数奇点
 $a_k \neq \frac{f^{(k)}(z_0)}{k!}$
洛朗级数是唯一的.

1) $\frac{\sin z}{z}$ ① $f(z) = \sum_{n=0}^{\infty} a_n z^n$, $a_n = \frac{1}{2\pi i} \oint_C \frac{\sin \zeta}{\zeta^{n+1}} d\zeta$ ($|z| > 0$), 此时所有负幂次项均为0

② $f(z) = \frac{z - \frac{z^3}{3!} + \frac{z^5}{5!} - \dots}{z} = 1 - \frac{z^2}{3!} + \frac{z^4}{5!} - \dots$ 只有正幂次的洛朗展开

$f(z)$ 相同。
由于洛朗展开唯一

def $F(z) = \int \frac{f(z) - \frac{\sin z}{z}}{|z|} dz$ 解析延拓

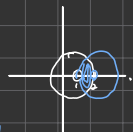
2) $f(z) = \frac{1}{(z-1)(z-2)}$

$0 < |z-1| < 1$

有限负幂次项

Laurent's 展开 $\Rightarrow f(z) = \frac{1}{z-1} - \frac{1}{z-2} = \frac{1}{z-1} - \frac{1}{(z-1)-1} = -\frac{1}{1-(z-1)} - \frac{1}{z-1} = -\sum_{k=0}^{\infty} (z-1)^k - \frac{1}{z-1} = -\sum_{k=-1}^{\infty} (z-1)^k$

Laurent's 展开 $\Rightarrow f(z) = \frac{1}{z-1} - \frac{1}{z-2} = (z-2)^{-1} + \sum_{k=1}^{\infty} (-1)^k (z-2)^k = \sum_{k=-1}^{\infty} (-1)^{k+1} (z-2)^k$



3) $f(z) = e^{\frac{1}{z}} = \sum_{k=0}^{\infty} \frac{1}{k!} \left(\frac{1}{z}\right)^k = \sum_{k=0}^{\infty} \frac{1}{(-k)!} z^k$ ($|z| > 0$) 无穷负幂次项

4) $f(z) = e^{\frac{1}{2}z(z-\frac{1}{2})}$ (n 为整数)

$e^{\frac{1}{2}z(z-\frac{1}{2})} = e^{\frac{1}{2}z^2} \cdot e^{-\frac{1}{4}z}$

$= \sum_{k=0}^{\infty} \frac{1}{k!} \left(\frac{1}{2}z\right)^k \cdot \sum_{n=0}^{\infty} \frac{1}{n!} \left(-\frac{1}{4}z\right)^n$ ($0 < |z| < \infty$)

$= \sum_{m=0}^{\infty} J_m(x) z^m$

$\triangle$
 m 阶 Bessel 函数

§3.6 奇点分类

1) 孤立奇点 $\neq$ 非孤立奇点

挖去后展为洛朗级数 在 z_0 邻域内 总有不可奇点
(为解析函数)

2) 孤立奇点分类

① 可去奇点 只有正幂次项

$\lim_{z \rightarrow z_0} (z-z_0)^m f(z)$ 有限

② 极点 有有限个负幂次项 $\rightarrow \sum_{n=-m}^{\infty} a_n (z-z_0)^n$ ($0 < |z-z_0| < R$) m 为极点 z_0 的阶数。一阶极点称为单极点

③ 本性奇点 有无限个负幂次项

$$f(z) = \sum_{k=0}^{\infty} a_k (z-z_0)^k \quad (0 < |z-z_0| < R)$$

$\lim_{z \rightarrow z_0} f(z)$ 由 $z \rightarrow z_0$ 路径决定

* 无限远点为孤立奇点

$$f(z) = \sum_{k=0}^{\infty} a_k z^k \quad (R < |z| < \infty) \quad \begin{cases} \text{正则: 解析部分} \\ \text{正则: 主要部分} + \text{无正则部分} \end{cases}$$

无正则项 $\rightarrow$ 可去奇点
有限正则项 $\rightarrow$ 极点
无限正则项 $\rightarrow$ 本性奇点

* 支点为孤立奇点

对有限阶支点, $m-1$ 阶支点 z_0 , 引入 $\zeta = \sqrt[m]{z-z_0}$, ζ 邻域为单叶圆环

$$g(\zeta) = \sum_{k=0}^{\infty} a_k \zeta^k = \sum_{k=0}^{\infty} a_k (z-z_0)^{k/m}$$

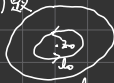
无奇点 有限奇点 无限奇点

解析型 极点型 本性奇点型
支点 支点 支点

§4 留数定理及应用

§4.1 留数定理

1) 定义

 $\oint_C f(z) dz = \oint_C f(z) dz \xrightarrow{\text{洛朗展开}} \sum_{k=0}^{\infty} a_k \oint_C (z-z_0)^k dz = 2\pi i a_{-1}$

所有负幂次项积分为0
(-1次项积分为 $2\pi i$ 时, 即为 $2\pi i$)

$f(z)$ 在 z_0 的留数 (残数), 记为 $\text{Res} f(z_0)$

$\oint_C f(z) dz = 2\pi i \text{Res} f(z_0)$

2) 留数定理: $f(z)$ 在回路 C 所围区域 B 上除有限个孤立奇点 $b_1, b_2, \dots, b_n$ 外解析, 在闭域 $\bar{B}$ 上除极点外连续

外连续

$$\text{则 } \oint_C f(z) dz = 2\pi i \sum_{j=1}^n \text{Res} f(b_j)$$

$$\text{无限远点留数为 } -a_{-1}, \text{ 即 } \text{Res} f(\infty), \text{ Res} f(\infty) = -2\pi i \sum_{j=1}^n \text{Res} f(z_j)$$

$f(z)$ 在全平面上各点 (包含无限远点和有限远点) 的留数之和为0

3) 留数计算

① 确定回路所有奇点

② 对极点 $z_j, j=1, 2, \dots, n$ 作 Laurent 展开, 求 a_{-1}

③ 确定奇点类型

1) 若为可去奇点, 则 $a_1=0$

若为极点, 判断极点阶数.

m 阶极点: $f(z) = a_m(z-z_0)^{-m} + \dots + a_1(z-z_0)^{-1} + a_0 + a_1(z-z_0) + \dots$

$$\lim_{z \rightarrow z_0} (z-z_0)^m f(z) = a_m \Rightarrow (z-z_0)^m f(z) = a_m + \dots + a_1(z-z_0)^{m-1} + a_0(z-z_0)^m + \dots$$

$$\Rightarrow \lim_{z \rightarrow z_0} \frac{d^{m-1}}{dz^{m-1}} [(z-z_0)^m f(z)] = (m-1)! a_{-1} \Rightarrow \text{Res } f(z_0) = \frac{1}{(m-1)!} \lim_{z \rightarrow z_0} \frac{d^{m-1}}{dz^{m-1}} [(z-z_0)^m f(z)]$$

3) 若为本性奇点, 则考虑 $a_1(z-z_0)^{-1}$

Alternate descriptions 1 edit

Let a be a complex number, assume that $f(z)$ is not defined at a but is analytic in some region U of the complex plane, and that every open neighbourhood of a has non-empty intersection with U .

If both

$$\lim_{z \rightarrow a} f(z) \text{ and } \lim_{z \rightarrow a} \frac{1}{f(z)}$$

exist, then a is a removable singularity of both f and $1/f$.

If

$$\lim_{z \rightarrow a} f(z) \text{ exists but } \lim_{z \rightarrow a} \frac{1}{f(z)}$$

does not exist, then a is a zero of f and a pole of $1/f$.

Similarly, if

$$\lim_{z \rightarrow a} f(z) \text{ does not exist but } \lim_{z \rightarrow a} \frac{1}{f(z)}$$

exists, then a is a pole of f and a zero of $1/f$.

If neither

$$\lim_{z \rightarrow a} f(z) \text{ nor } \lim_{z \rightarrow a} \frac{1}{f(z)}$$

exists, then a is an essential singularity of both f and $1/f$.

Another way to characterize an essential singularity is that the Laurent series of f at the point a has infinitely many negative degree terms (i.e., the principal part of the Laurent series is an infinite sum). A related definition is that if there is a point a for which no derivative of $f(z)(z-a)^n$ converges to a limit as z tends to a , then a is an essential singularity of $f(z)$.^[1]

The behavior of holomorphic functions near their essential singularities is described by the Casorati–Weierstrass theorem at $\frac{1}{z-1}$ in [Complex analysis: the Casorati–Weierstrass theorem](#). The latter says that in every neighborhood of an essential singularity, a function takes on every complex value, [except for at most one value](#), [infinitely many times](#). (The exception is necessary, as the function $\exp(1/z)$ never takes on the value 0.)



Model illustrating essential singularity of a complex function (arXiv:1110.0202)

or 判断是否为 pole

$\lim_{z \rightarrow z_0} (z-z_0)^n f(z)$ 是否 $\neq 0$

$\frac{1}{\sin z}$ 奇点 $n\pi$. 留数为 $(-1)^n$.
 $\text{Res}(\infty)$ 不定.

§4.2 应用留数定理 计算实变函数定积分

$$\int_a^b f(x) dx \mapsto \oint f(z) dz = 2\pi i \sum \text{Res } f(z_j)$$

法1: 映射

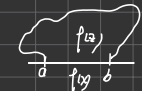
$$x \mapsto z$$

$$f(x) \mapsto f(z)$$

$$a \rightarrow b \mapsto \text{回路}$$

$$\int_0^{2\pi} R(\cos x, \sin x) dx \stackrel{z=e^{ix}}{=} \oint_{|z|=1} R\left(\frac{z+z^{-1}}{2}, \frac{z-z^{-1}}{2}\right) \frac{1}{iz} dz$$

法2: 延拓



$$\oint f(z) dz = \int_a^b f(x) dx + \int_{b \rightarrow a} f(z) dz + \dots = 2\pi i \sum \text{Res } f(z_j)$$

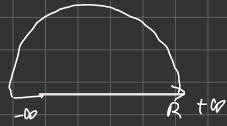
设置 $\int_{\gamma} f(z) dz$ $\begin{cases} \text{为 } 0 \\ \text{简单} \\ \text{为 } \int_a^b f(x) dx \text{ 形式 (倍乘形式)} \end{cases}$

类型 I

$$\int_0^{2\pi} R(\cos \theta, \sin \theta) d\theta \quad z = e^{i\theta} \quad d\theta = \frac{1}{iz} dz$$

类型 II

$$\int_{-\infty}^{+\infty} f(x) dx + \int_{CR} f(z) dz = 2\pi i \sum_{j=1}^n \text{Res} f(z_j)$$



$z f(z) \xrightarrow{\text{一致趋于}} 0$ 当 $|z| \rightarrow \infty$ 满足 实轴上无奇点. 上半平面 除有限个奇点外解析

$$\left| \int_{CR} f(z) dz \right| = \int_{CR} |f(z)| |dz| \leq \max_{CR} |f(z)| \underbrace{\left| \int_{CR} \frac{dz}{z} \right|}_{\int_0^\pi \frac{1}{e^{i\theta}} \cdot i e^{i\theta} d\theta} = \max_{CR} |f(z)| \pi \Rightarrow 0$$

类型 III

$$\int_0^{+\infty} F(x) \cos mx dx, \quad \int_0^{+\infty} G(x) \sin mx dx$$

满足 $z \rightarrow \infty, F(z), G(z) \rightarrow 0$

$$\pi i \sum_{j=1}^k \text{Res} (F(z) e^{imz})$$

$$\begin{aligned} \frac{1}{2} \int_{-\infty}^{+\infty} F(x) \cos mx dx &= \frac{1}{2} \int_{-\infty}^{+\infty} F(x) \frac{e^{imx} + e^{-imx}}{2} dx \stackrel{F(x)=F(\bar{x})}{=} \frac{1}{2} \int_{-\infty}^{+\infty} F(x) e^{imx} dx + \frac{1}{2} \int_{CR} F(z) e^{imz} dz \\ \frac{1}{2} \int_{-\infty}^{+\infty} G(x) \sin mx dx &= \frac{1}{2} \int_{-\infty}^{+\infty} G(x) \frac{e^{imx} - e^{-imx}}{2i} dx \stackrel{G(x)=G(\bar{x})}{=} \frac{1}{2i} \int_{-\infty}^{+\infty} G(x) e^{imx} dx + \frac{1}{2i} \int_{CR} G(z) e^{imz} dz \end{aligned}$$

$$\pi \sum_{j=1}^k \text{Res} (G(z) e^{imz})$$

注: $m > 0, m < 0$ 需分情况讨论

$$\oint_{CR} \left(-\pi i \sum_{j=1}^k \text{Res} f(z_j) \right)$$

约当引理 (Jordan's Lemma)

$f(z)$ 在 $\theta_1 \leq \arg z \leq \theta_2, R < |z| < \infty$ 上连续且 $\lim_{z \rightarrow \infty} f(z) = 0$

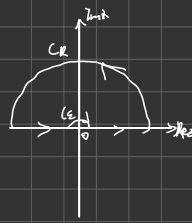
$$\forall \epsilon > 0 \exists M > 0, \lim_{R \rightarrow \infty} \int_{CR} f(z) e^{imz} dz = 0$$

$$\begin{aligned} \left| \int_{CR} f(z) e^{imz} dz \right| &= \left| \int_{\theta_1}^{\theta_2} f(Re^{i\theta}) e^{imRe^{i\theta}} dRe^{i\theta} \right| \leq \int_{\theta_1}^{\theta_2} |f(Re^{i\theta})| e^{-mR \sin \theta} R d\theta \\ &\leq \int_0^\pi |f(Re^{i\theta})| e^{-mR \sin \theta} R d\theta \leq \max |f(z)| R \int_0^\pi e^{-mR \sin \theta} d\theta \\ &= 2 \max |f(z)| R \int_0^{\frac{\pi}{2}} e^{-mR \sin \theta} d\theta \leq 2 \max |f(z)| R \int_0^{\frac{\pi}{2}} e^{-mR \frac{2}{\pi} \theta} d\theta \\ &\leq \frac{1}{m\pi} \cdot 2 \max |f(z)| \Rightarrow 0 \end{aligned}$$

ep. 实轴上单极点情况

$$\int_0^{\infty} \frac{\sin x}{x} dx = \frac{1}{2i} \int_{-\infty}^{\infty} \frac{e^{-i\pi}}{z} dz = I = -\frac{1}{2i} \int_{C_R} \frac{e^{iz}}{z} dz = \frac{\pi}{2}$$

$$\frac{1}{2i} \int_{-\infty}^{\infty} \frac{e^{iz}}{z} dz = \frac{1}{2i} \int_{C_R} \frac{e^{iz}}{z} dz + \frac{1}{2i} \int_0^{\infty} \frac{e^{iz}}{z} dz + \frac{1}{2i} \int_{C_R} \frac{e^{iz}}{z} dz + \frac{1}{2i} \int_{-\infty}^{\infty} \frac{e^{iz}}{z} dz = 0$$



$\int_{-\infty}^{\infty} f(x) dx = 2\pi i \sum_{\text{上半平面}} \text{Res} f(z) + \pi i \sum_{\text{实轴}} \text{Res} f(z)$

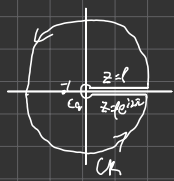
$$\begin{aligned} &= \frac{1}{2i} \int_0^{\infty} \frac{e^{iz}}{z} e^{i\pi} dz \\ &= \frac{1}{2i} \int_0^{\infty} \frac{e^{iz}}{z} e^{i\pi} dz \\ &= \frac{\pi}{2i} \int_0^{\infty} (1 + i\pi e^{iz}) dz \\ &= \frac{1}{2i} (-i\pi) = -\frac{\pi}{2} \end{aligned}$$

§ 4.3 补充

ep. $I = \int_0^{\infty} x^{\alpha-1} \frac{1}{1+x} dx \quad (0 < \alpha < 1)$

$(z \cdot z^{\alpha-1} \frac{1}{1+z} \rightarrow 0)$

对 $f(z) = z^{\alpha-1} \frac{1}{1+z}$, $z=0$ 为支点, $z=-1$ 为单极点



$$\begin{aligned} &\int_{C_R} \frac{z^{\alpha-1}}{1+z} dz + \int_{C_R'} \frac{z^{\alpha-1}}{1+z} dz + \int_{C_1} \frac{z^{\alpha-1}}{1+z} dz + \int_{C_2} \frac{z^{\alpha-1}}{1+z} dz = (1 - e^{i2\pi\alpha}) I \\ &= 2\pi i \text{Res} f(-1) \\ &= 2\pi i (-1)^{\alpha-1} \end{aligned}$$

$$\begin{aligned} \frac{e^{i\pi\alpha} (1 - e^{i2\pi\alpha})}{2i} I &= \pi e^{i\pi\alpha} \\ &= \pi \sin \pi\alpha \\ I &= \frac{\pi}{\sin \pi\alpha} \end{aligned}$$

$I = \int_0^{\infty} \frac{x^{\alpha-1}}{1+x} dx = \pi \tan \frac{\pi\alpha}{2} = \pi \frac{\sin \pi\alpha}{\cos \pi\alpha}$

计算 $\int_0^{\infty} f(x) \ln x dx$

考虑 $\oint f(z) \ln z dz = 4\pi i \int_0^{\infty} f(x) \ln x dx - 4\pi i \int_0^{\infty} f(x) dx$

下面简单介绍一下色散关系。对于在上半平面处处解析的函数 $f(z)$ ，如果当 $z \rightarrow \infty$ 时， $f(z) \rightarrow 0$ (即 $\text{Arg } z \leq \pi$)， α 为一实数，则按照 (4.2.12)，

$$\oint_{-\infty}^{\infty} \frac{f(x)}{x-\alpha} dx = \pi i \cdot \left\{ \frac{f(z)}{z-\alpha} \text{ 在 } \alpha \text{ 的留数} \right\} = \pi i f(\alpha).$$

分别写出实部和虚部

$$\text{Re } f(\alpha) = \frac{1}{\pi} \oint_{-\infty}^{\infty} \frac{\text{Im } f(x)}{x-\alpha} dx, \quad (4.2.15)$$

$$\text{Im } f(\alpha) = -\frac{1}{\pi} \oint_{-\infty}^{\infty} \frac{\text{Re } f(x)}{x-\alpha} dx. \quad (4.2.16)$$

这一对关系式在数学上称为希爾伯特 (Hilbert, 1862—1943) 变换，在物理上称为色散关系。

$\int_0^{+\infty} f(x) dx$ 型积分

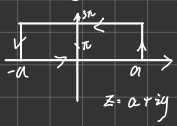
此时 f 不是偶函数，下面我们不加证明的给出两个定理

定理 5. 设 $f(z)$ 在 $\mathbb{C} \setminus [0, +\infty)$ 上除去点 $a_1, a_2, \dots, a_n$ 外全纯，连续到正实轴，若 $\lim_{z \rightarrow \infty} |z|^p f(z) = 0$ ($p > 0$)，则

$$\int_0^{+\infty} f(x) x^{p-1} dx = \frac{2\pi i}{1 - e^{2\pi p}} \sum_{k=1}^n \text{Res}(z^{p-1} f(z), a_k)$$

其中 $z^{p-1} = |z|^{p-1} e^{i(p-1)\arg z}$, $0 < \arg z < 2\pi$.

ex3.
$$I = \int_{-\infty}^{\infty} \frac{e^{ax}}{1+e^x} dx \quad 0 < a < 1$$

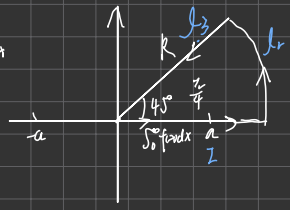


ex4. 计算复变积分
(Prestel integral)

$$I_1 = \int_0^{\pi} \sin x dx \quad I_2 = \int_0^{\pi} \cos x dx$$

$$f(z) = e^{iaz}$$

$$\int_0^{\infty} f(x) dx = I_2 + i I_1$$



55 傅立叶变换 (Fourier Transformation)

若 $l \rightarrow \infty$ $f(x) = f(x+2l)$ 即非周期函数.

则可先展开, 再令 $l \rightarrow \infty$.

$$f(x) = a_0 + \sum_{n=1}^{\infty} a_n \cos nx + \sum_{n=1}^{\infty} b_n \sin nx$$

$$a_0 = \frac{1}{2l} \int_{-l}^l f(x) dx \xrightarrow{l \rightarrow \infty} 0$$

$$a_n = \lim_{l \rightarrow \infty} \frac{1}{l} \int_{-l}^l f(x) \cos nx dx$$

$$b_n = \lim_{l \rightarrow \infty} \frac{1}{l} \int_{-l}^l f(x) \sin nx dx$$

$$\sum_{n=1}^{\infty} \lim_{l \rightarrow \infty} \frac{1}{l} \int_{-l}^l f(x) \cos nx dx \cdot \cos nx$$

$$= \frac{1}{\pi} \sum_{n=1}^{\infty} \lim_{l \rightarrow \infty} \int_{-l}^l f(x) \cos nx dx \cos nx \frac{dx}{dx}$$

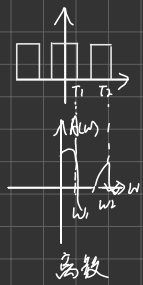
$$= \frac{1}{\pi} \sum_{n=1}^{\infty} \int_0^{\infty} \int_{-\infty}^{\infty} f(x) \cos nx dx \cos nx dw$$

$$= \frac{1}{\pi} \sum_{n=1}^{\infty} \int_0^{\infty} A(w) \cos nx dw$$

↓

$$f(x) = \int_0^{\infty} A(w) \cos wx dw + \int_0^{\infty} B(w) \sin wx dw$$

$$\begin{cases} A(w) = \frac{1}{\pi} \int_{-\infty}^{\infty} f(x) \cos wx dx \\ B(w) = \frac{1}{\pi} \int_{-\infty}^{\infty} f(x) \sin wx dx \end{cases}$$



频谱

函数

$$\oint f(z) dz = 0 = I + \int_{R \rightarrow \infty} f(z) dz + \int_{R \rightarrow \infty} f(z) dz$$

$$= I + \int_0^{\pi/4} R e^{it} e^{ia R e^{it}} i R e^{it} dt$$

$$+ \int_{\pi/4}^0 e^{it} e^{ia R e^{it}} e^{it} dt$$

$$e^{i\pi/4} \int_0^{\pi/4} e^{it} dt = e^{i\pi/4} \frac{R}{2}$$

$$\left| \int_0^{\pi/4} e^{it} e^{ia R e^{it}} i R e^{it} dt \right| < \int_0^{\pi/4} e^{-R \sin t} R dt$$

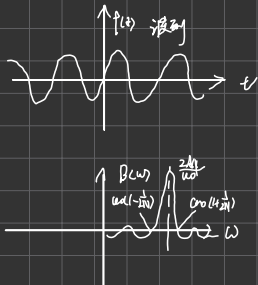
$$< \int_0^{\pi/4} e^{-\frac{R}{2} t} R dt$$

$$= \frac{R}{4R} (e^{-\frac{R}{2}} - 1) \rightarrow 0$$

$$\Rightarrow 0 = I + e^{i\pi/4} \frac{R}{2}$$

$$I = -\frac{\sqrt{2}}{4} - i \frac{\sqrt{2}}{4}$$

ep. $f_{\omega} = \begin{cases} 0 & t < -\frac{N\pi}{\omega_0} \\ A \sin \omega_0 t & -\frac{N\pi}{\omega_0} < t < \frac{N\pi}{\omega_0} \\ 0 & t > \frac{N\pi}{\omega_0} \end{cases}$



$$\begin{aligned} \Phi(\omega) &= \frac{1}{\pi} \int_{-\infty}^{\infty} f(t) \sin \omega t dt \\ &= \frac{1}{\pi} \int_{-\frac{N\pi}{\omega_0}}^{\frac{N\pi}{\omega_0}} A \sin \omega_0 t \sin \omega t dt \\ &= \frac{A}{\pi} \int_{-\frac{N\pi}{\omega_0}}^{\frac{N\pi}{\omega_0}} [\cos(\omega_0 t - \omega t) - \cos(\omega_0 t + \omega t)] dt \\ &= \frac{2A\omega_0}{\pi(\omega^2 - \omega_0^2)} \sin(N\pi \frac{\omega}{\omega_0}) \end{aligned}$$

复数形式 Fourier transformation

$$f(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} F(\omega) e^{i\omega x} d\omega$$

$$F(\omega) = \overline{f(x)} = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f(x) e^{-i\omega x} dx$$

$$\frac{1}{2\pi} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x) e^{-i\omega x} e^{i\omega x} d\omega dx$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} f(x) dx \int_{-\infty}^{\infty} e^{i\omega(x-x)} d\omega = \frac{1}{2\pi} \int_{-\infty}^{\infty} f(x) dx \int_{-\infty}^{\infty} e^{i\omega(x-x)} d\omega$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} f(x) dx \cdot \underbrace{2\pi \delta(x-x)}_{\substack{\infty \quad 0 \\ x=g \quad x \neq g}} = \int_{-\infty}^{\infty} f(x) \delta(x-g) dx = \int_{-\infty}^{\infty} f(x) \delta(x-g) dx = f(g)$$

傅立叶变换性质

1) 导数定理: $\widetilde{F}[f'(x)] = i\omega F(\omega)$

$$\widetilde{F}[f(x)] = i\omega F(\omega)$$

2) 积分定理:

$$\widetilde{F}\left[\int_{-\infty}^x f(\xi) d\xi\right] = \frac{F(\omega)}{i\omega}$$

3) 延迟定理

$$\widetilde{F}[f(x-x_0)] = e^{-i\omega x_0} F(\omega)$$

4) 位移定理

$$\widetilde{F}[e^{i\omega_0 x} f(x)] = F(\omega - \omega_0)$$

5) 相似定理

$$\widetilde{F}[f(ax)] = \frac{1}{|a|} F\left(\frac{\omega}{a}\right)$$

6) 卷积定理

$$\widetilde{F}\left[\int_{-\infty}^{\infty} f_1(\xi) f_2(x-\xi) d\xi\right] = 2\pi F_1(\omega) F_2(\omega)$$

eq. $y''(x) + k^2 y(x) = A \sin \omega x$

$$\begin{aligned} \Downarrow \\ -\omega^2 Y(\omega) + k^2 Y(\omega) &= \frac{A}{\sqrt{2\pi}} \int_{-\infty}^{+\infty} \frac{e^{ix\omega_0 - ix\omega}}{ix} e^{-ixx} dx \\ &= \frac{A}{\sqrt{2\pi}} \frac{1}{i\omega} \int_{-\infty}^{+\infty} [e^{ix(\omega_0 - \omega)} - e^{-ix(\omega_0 + \omega)}] dx \\ &= \frac{A}{\sqrt{2\pi}} \frac{1}{i\omega} \cdot 2\pi [\delta(\omega_0 - \omega) - \delta(\omega_0 + \omega)] \\ &= \tilde{F}[A \sin \omega_0 x] \end{aligned}$$

$$Y(\omega) = \frac{\tilde{F}[A \sin \omega_0 x]}{k^2 - \omega^2}$$

$$\begin{aligned} y(x) &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{+\infty} Y(\omega) e^{i\omega x} d\omega \\ &= C \frac{i}{k^2 - \omega^2} A \sin \omega_0 x \end{aligned}$$

三维空间的 Fourier Transformation

$$f(\vec{r}) = f(x, y, z) = \frac{1}{(2\pi)^{3/2}} \iiint F(\vec{k}) e^{i\vec{k} \cdot \vec{r}} d^3\vec{k}$$

$$\begin{aligned} F(\vec{k}) &= \frac{1}{(2\pi)^{3/2}} \iiint f(\vec{r}) e^{-i\vec{k} \cdot \vec{r}} d^3\vec{r} \\ &= \frac{1}{(2\pi)^{3/2}} \iiint f(x, y, z) e^{-ik_x x - ik_y y - ik_z z} dx dy dz \end{aligned}$$

§5.3 $\delta(x)$ 函数

Question 1: 证明一个质点与一个均匀球壳间引力等于该质点与球壳质量相同的位于球心处的质点

引力相同

Question 2: Submarine 是否对周围引力场有改变

引入 理想模型

质点, 点电荷, 瞬时力

函数.

$$\delta(x - x_0) = \begin{cases} 0 & x \neq x_0 \\ \infty & x = x_0 \end{cases} \quad \int_a^b \delta(x - x_0) dx = \begin{cases} 1 & a < x_0 < b \\ 0 & b < x_0 \text{ 或 } a > x_0 \end{cases} \quad \delta(x) \text{ 量纲 } [\delta(x)] = 1/x$$

性质① $\delta(x)$ 为偶函数

$$\delta(x) = \delta(-x)$$

② 积分是 Step 函数

$$\int_{-\infty}^x \delta(x - x_0) dx = \begin{cases} 0 & x < x_0 \\ 1 & x > x_0 \end{cases}$$

$$\begin{aligned} \text{Def } H(x) &= \int_{-\infty}^x \delta(x - x_0) dx \\ \frac{dH(x)}{dx} &= \delta(x - x_0) \end{aligned}$$

③ 透射性

$$\int_a^b f(x) \delta(x - x_0) dx = f(x_0) \quad \text{when } x_0 \in (a, b)$$

$$\int_a^b f(x) \delta(x - x_0) dx = f(x_0) \quad \text{when } x_0 \in (a, b)$$

$$\textcircled{4} \delta[f(x)] = \begin{cases} 0 & f(x) \neq 0 \\ \infty & f(x) = 0 \end{cases}$$

$$\varphi(x) = \prod_k (x - x_k)$$

$$\delta[\varphi(x)] = \sum_k C_k \delta(x - x_k)$$

$$\begin{aligned} \int_{x_{k-1}}^{x_{k+1}} \delta[\varphi(x)] dx &= \int_{x_{k-1}}^{x_{k+1}} \sum_l C_l \delta(x - x_l) dx = \int_{x_{k-1}}^{x_{k+1}} C_k \delta(x - x_k) dx \\ &= \int_{x_{k-1}}^{x_{k+1}} \frac{\delta[\varphi(x)]}{|\varphi'(x)|} dx = \frac{1}{|\varphi'(x_k)|} = C_k \end{aligned}$$

$$\delta(x-a) = \frac{\delta(x-a)}{2|a|} + \frac{\delta(x+a)}{2|a|}$$

$$\delta(x) = \frac{\delta(x)}{|x|}$$

② 傅立叶变换.

$$\delta(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} C(\omega) e^{i\omega x} d\omega = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{i\omega x} d\omega$$

$$C(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \delta(x) e^{-i\omega x} dx$$

$$= \frac{1}{\sqrt{2\pi}}$$

③ $\delta(x)$ 可由多种基函数的极限来表示.

$$\textcircled{1} \delta(x) = \lim_{k \rightarrow \infty} \frac{1}{\sqrt{2\pi}} \int_{-k}^k e^{-i\omega x} d\omega$$

$$= \lim_{k \rightarrow \infty} \frac{1}{\sqrt{2\pi}} \cdot \frac{1}{i\omega} \cdot e^{-i\omega x} \Big|_{-k}^k$$

$$= \lim_{k \rightarrow \infty} \frac{1}{\sqrt{2\pi}} (e^{-i\omega x} - e^{-i\omega x})$$

$$= \lim_{k \rightarrow \infty} \frac{\sin kx}{\pi x}$$

$$\textcircled{2} \delta(x) = \lim_{k \rightarrow \infty} \frac{1}{\sqrt{2\pi}} \left[\int_{-k}^0 e^{(k+i\omega)x} d\omega + \int_0^{\infty} e^{-(k+i\omega)x} d\omega \right]$$

$$= \lim_{k \rightarrow \infty} \frac{1}{\sqrt{2\pi}} \left[\frac{1}{k+i\omega} \Big|_{-k}^0 + \frac{1}{-k-i\omega} \Big|_0^{\infty} \right]$$

$$= \frac{1}{\sqrt{2\pi}} \lim_{k \rightarrow \infty} \frac{2k}{k^2 + \omega^2}$$

$$= \lim_{k \rightarrow \infty} \frac{2}{k} \frac{1}{1 + \frac{\omega^2}{k^2}}$$

$$\textcircled{3} \delta(x) = \lim_{k \rightarrow \infty} \frac{1}{\sqrt{2\pi}} e^{-x^2/2k^2}$$

④ 高维.

$$\delta(\vec{r} - \vec{r}_0) = \begin{cases} 0 & \vec{r} \neq \vec{r}_0 \\ \infty & \vec{r} = \vec{r}_0 \end{cases}$$

$$\int \delta(\vec{r} - \vec{r}_0) d^3\vec{r} = 1$$

$$\delta(\vec{r} - \vec{r}_0) = \delta(x-x_0) \delta(y-y_0) \delta(z-z_0) \quad \text{坐标点}$$

$$\delta(\vec{r} - \vec{r}_0) = \frac{1}{\rho} \delta(\rho - \rho_0) \delta(\phi - \phi_0) \delta(z - z_0) \quad \text{柱坐标}$$

$$\delta(\vec{r} - \vec{r}_0) = \frac{1}{r^2 \sin \theta} \delta(r - r_0) \delta(\theta - \theta_0) \delta(\phi - \phi_0) \quad \text{球坐标}$$

ep.

§6. 拉普拉斯变换 (Laplace transformation) (LT)

§6.1

For Fourier Transformation

$$\mathcal{F}[y(x)] = \bar{y}(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} y(x) e^{-i\omega x} dx$$

$$y'(x) + p y(x) = f(x)$$

$$y(x) = \mathcal{F}^{-1}[\bar{y}(\omega)] = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \bar{y}(\omega) e^{i\omega x} d\omega$$

$$(i\omega) \bar{y}(\omega) + (i\omega) p \bar{y}(\omega) = \bar{f}(\omega)$$

$$\bar{y}(\omega) = \bar{f}(\omega) / (-i\omega^2 + i\omega p + q)$$

For Laplace Transformation

$$\text{Def } \int_0^{\infty} y(t) dt, \quad t > 0 \quad \text{or } y(t) H(t) \quad H(t) = \begin{cases} 1 & t > 0 \\ 0 & t < 0 \end{cases}$$

$$\mathcal{L}[y(t)] = \bar{y}(p) = \int_0^{\infty} y(t) e^{-pt} dt \quad y(t) = \mathcal{L}^{-1}[\bar{y}(p)]$$

$$y(t) = \mathcal{L}^{-1}[\bar{y}(p)] = \frac{1}{2\pi i} \int_{\sigma - i\infty}^{\sigma + i\infty} \bar{y}(p) e^{pt} dp \quad \bar{y}(p) = \mathcal{L}[y(t)]$$

$$\text{def } p = \sigma + i\omega$$

$$\mathcal{L}(1) = \mathcal{L}[H(t)] = \int_0^{\infty} e^{-pt} dt = \frac{1}{p}$$

$$\mathcal{L}(t^n) = \mathcal{L}(t^n H(t)) = \int_0^{\infty} t^n e^{-pt} dt = \frac{1}{p} \int_0^{\infty} t^n d e^{-pt} = \frac{1}{p} \left[t^n e^{-pt} \Big|_0^{\infty} - n \int_0^{\infty} e^{-pt} t^{n-1} dt \right] = \frac{n}{p} \int_0^{\infty} e^{-pt} t^{n-1} dt = \frac{n}{p} \mathcal{L}[t^{n-1}]$$

$$\mathcal{L}^{-1}\left[\frac{1}{p}\right] = H(t) \quad \mathcal{L}^{-1}\left[\frac{n!}{p^{n+1}}\right] = \frac{n!}{p^{n+1}} \mathcal{L}[t^n] = \dots = \frac{n!}{p^{n+1}}$$

$$\mathcal{L}^{-1}\left[\frac{1}{p^{n+1}}\right] = \frac{t^n}{n!}$$

$$\mathcal{L}[e^{st}] = \int_0^{\infty} e^{st} e^{-pt} dt = \frac{1}{s-p} \int_0^{\infty} e^{(s-p)t} dt = \frac{1}{p-s}$$

$$\mathcal{L}[t^n e^{st}] = \int_0^{\infty} e^{st} t^n e^{-pt} dt = \frac{n!}{(p-s)^{n+1}}$$

性质: ① $\mathcal{L}[c_1 \varphi(t) + c_2 \psi(t)] = c_1 \mathcal{L}[\varphi(t)] + c_2 \mathcal{L}[\psi(t)]$ 线性性.

$$\mathcal{L}(\sin \omega t) = \mathcal{L}\left[\frac{1}{2j}(e^{j\omega t} - e^{-j\omega t})\right] = \frac{1}{2j} \left[\frac{1}{p-j\omega} - \frac{1}{p+j\omega} \right] = \frac{\omega}{p^2 + \omega^2}$$

$$\mathcal{L}(\cos \omega t) = \mathcal{L}\left[\frac{1}{2}(e^{j\omega t} + e^{-j\omega t})\right] = \frac{1}{2} \left[\frac{1}{p-j\omega} + \frac{1}{p+j\omega} \right] = \frac{p}{p^2 + \omega^2}$$

② 导数定理

$$\mathcal{L}\left(\frac{dy(t)}{dt}\right) = \int_0^{\infty} \frac{dy(t)}{dt} e^{-pt} dt = y(t) e^{-pt} \Big|_0^{\infty} + p \int_0^{\infty} y(t) e^{-pt} dt = -y(0) + p \mathcal{L}[y(t)]$$

$$\Rightarrow \mathcal{L}\left[\frac{dy(t)}{dt}\right] = p \mathcal{L}[y(t)] - y(0)$$

or

$$\bar{y}(p) = p \bar{y}(p) - y(0)$$

$$\mathcal{L}[y^{(n)}(t)] = p^n \mathcal{L}[y(t)] - p^{n-1} y(0) - p^{n-2} y'(0) - \dots - y^{(n-1)}(0)$$

③ 积分定理

$$y(t) = \int_0^t \varphi(z) dz \quad (t > 0)$$

$$\begin{aligned} \mathcal{L}\left[\int_0^t \varphi(z) dz\right] &= \int_0^{\infty} \int_0^t \varphi(z) dz e^{-pt} dt = \frac{1}{p} \int_0^{\infty} \int_0^t \varphi(z) dz d e^{-pt} = -\frac{1}{p} \left[\int_0^t \varphi(z) dz e^{-pt} \Big|_0^{\infty} - \int_0^{\infty} e^{-pt} \varphi(t) dt \right] \\ &= \frac{1}{p} \mathcal{L}[\varphi(t)] \end{aligned}$$

$$\begin{cases} y''(t) + a y'(t) + b y(t) = \bar{f}(t) \\ y(0) = k_1, \quad y'(0) = k_2 \end{cases}$$

$$\Rightarrow [p^2 \bar{y}(p) - p y(0) - y'(0)] + a [p \bar{y}(p) - y(0)] + b \bar{y}(p) = \bar{f}(p)$$

$$(p^2 + a p + b) \bar{y}(p) = \bar{f}(p) + (p + a) k_1 + k_2$$

$$\bar{y}(p) = \frac{\bar{f}(p) + (p + a) k_1 + k_2}{p^2 + a p + b}$$

$$y(t) = \mathcal{L}^{-1}[\bar{y}(p)]$$

$$\bar{y}(p) = \int_0^{\infty} e^{-pt} y(t) dt$$

$$\frac{d\bar{y}(p)}{dp} = - \int_0^{\infty} e^{-pt} t y(t) dt$$

$$\mathcal{L}[t y(t)] = - \frac{d\bar{y}(p)}{dp}$$

$$\textcircled{2} \mathcal{L}[t^n y(t)] = (-1)^n \frac{d^n \bar{y}(p)}{dp^n}$$

$$\mathcal{L}[e^{st}] = \frac{1}{p-s}$$

$$\mathcal{L}[t e^{st}] = \frac{1}{(p-s)^2}$$

⋮

$$\mathcal{L}[t^n e^{st}] = \frac{n!}{(p-s)^{n+1}}$$

$$\begin{cases} y''(t) + (1-n)y'(t) + y(t) = 0 \\ y(0) = 0, \quad y'(0) = \infty \end{cases}$$

$$\mathcal{L}(y''(t)) = p^2 \bar{y}(p) - p y'(0) - y(0)$$

$$\mathcal{L}(t^n y(t)) = - \frac{d}{dp} [p^n \bar{y}(p)]$$

$$- \frac{d}{dp} [p^n \bar{y}(p)] + (1-n)p \bar{y}(p) + \bar{y}(p) = 0$$

$$-2p \bar{y}(p) - p^2 \frac{d\bar{y}(p)}{dp} + (1-n)p \bar{y}(p) + \bar{y}(p) = 0$$

$$\frac{d\bar{y}(p)}{\bar{y}(p)} = \frac{-2p(1-n)p+1}{p^2} = \frac{1-(n+1)p}{p^2}$$

$$\ln \bar{y}(p) = -\frac{1}{p} - \ln p^{n+1} + C$$

$$\bar{y}(p) = \frac{C}{p^{n+1}} e^{-\frac{1}{p}}$$

$$y(t) = \mathcal{L}^{-1}[\bar{y}(p)]$$

§ 6.2 Laplace 变换方法

$$\bar{y}(p) = \frac{1}{p} \quad y(t) = H(t)$$

$$\bar{y}(p) = \frac{1}{p^{n+1}} \quad y(t) = \frac{t^n}{n!}$$

$$\bar{y}(p) = \frac{1}{(p-s)^{n+1}} \quad y(t) = \frac{t^n}{n!} e^{st}$$

$$\bar{y}(p) = \frac{\omega}{p^2 + \omega^2} \quad y(t) = \sin \omega t$$

$$\bar{y}(p) = \frac{p}{p^2 + \omega^2} \quad y(t) = \cos \omega t$$

$$\begin{aligned} \bar{y}(p) &= \frac{1}{a^2 p^2 + b^2 p + c} \quad y(t) = \frac{2}{\sqrt{4ac-b^2}} e^{-\frac{b}{2a}t} \sin \frac{\sqrt{4ac-b^2}}{2a} t \\ &= \frac{1}{a(p+\frac{b}{2a})^2 + \sqrt{c-\frac{b^2}{4a}}} \end{aligned}$$

辅助反演定理

$$\bar{y}(p) = \bar{\varphi}(p)$$

① 延迟定理

$$e^{-\tau p} \bar{y}(p) = y(t-\tau)$$

$$\frac{1}{p} \longleftrightarrow \frac{1}{\sqrt{\pi s}}$$

$$\frac{e^{-\tau p}}{p} = \frac{1}{\sqrt{\pi(s-\tau)}}$$

② 位移定理

$$\bar{y}(p+\tau) = e^{-\tau t} y(t) \quad \bar{\varphi}(p+\tau) = e^{-\tau t} \varphi(t)$$

③ 卷积定理

$$\bar{y}(p) \bar{\varphi}(p) = \int_0^t y(\tau) \varphi(t-\tau) d\tau = \int_0^t \varphi(\omega) y(t-\omega) d\omega$$

$$\begin{aligned} \int_0^{\infty} \int_0^t \varphi(\tau) y(t-\tau) d\tau dt &= \int_0^{\infty} \varphi(\omega) d\omega \int_{\omega}^{\infty} y(t-\omega) e^{-pt} dt = \int_0^{\infty} \varphi(\omega) d\omega \int_0^{\infty} y(\tau) e^{-p(\tau+\omega)} e^{-p\omega} d\tau \\ &= \varphi(p) \int_0^{\infty} y(\tau) e^{-p\tau} d\tau \end{aligned}$$

黎曼-梅林反演公式

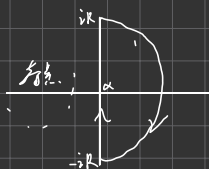
已知 $\overline{y(p)}$, 求 $\psi(t)$

$$\psi(t) = \frac{1}{2\pi i} \int_{\alpha-i\infty}^{\alpha+i\infty} \overline{y(p)} e^{pt} dp$$

积分路径在左侧

收敛定路大

路径从 ∞ 到 ∞



$$\overline{y(p)} = -\frac{1}{2\pi i} \oint \frac{\overline{y(s)}}{s-p} ds$$

$$= -\lim_{R \rightarrow \infty} \frac{1}{2\pi i} \int_{\alpha-iR}^{\alpha+iR} \frac{\overline{y(s)}}{s-p} ds - \underbrace{\lim_{R \rightarrow \infty} \frac{1}{R} \int_{\alpha-iR}^{\alpha+iR} \frac{\overline{y(s)}}{s-p} ds}$$

$$= \frac{1}{2\pi i} \int_{\alpha-i\infty}^{\alpha+i\infty} \frac{\overline{y(s)}}{s-p} ds$$

同时变换

$$\psi(t) = \frac{1}{2\pi i} \int_{\alpha-i\infty}^{\alpha+i\infty} \overline{y(s)} e^{st} ds$$

$$= \frac{1}{2\pi i} \int_{\alpha-i\infty}^{\alpha+i\infty} \overline{y(p)} e^{pt} dp$$

$$|\overline{y(s)}| < \frac{1}{s-p}$$

$$s-p \sim R e^{i\theta}$$

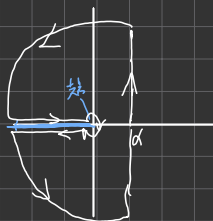
↓

$$R \sim \frac{1}{R} \int_0^{\infty} \frac{1}{R} \dots d\theta$$

→ 0

$$\overline{y(p)} = \frac{1}{\sqrt{p}} \text{ 求 } \psi(t)$$

$$\psi(t) = \frac{1}{2\pi i} \int_{\alpha-i\infty}^{\alpha+i\infty} \frac{1}{\sqrt{p}} e^{pt} dp$$



$$\oint \frac{1}{\sqrt{p}} e^{pt} dp = 0 = \psi(t) + \underbrace{\int_{\alpha-i\infty}^{\alpha+i\infty} \frac{1}{\sqrt{p}} e^{pt} dp}_{\rightarrow 0} + \underbrace{\int_{-i\infty}^{-i0} \frac{1}{\sqrt{p}} e^{pt} dp}_{\rightarrow 0} + \underbrace{\int_{0}^{i0} \frac{1}{\sqrt{p}} e^{pt} dp}_{\rightarrow 0} + \underbrace{\int_{i0}^{i\infty} \frac{1}{\sqrt{p}} e^{pt} dp}_{\rightarrow 0} + \underbrace{\int_{\alpha+i\infty}^{\alpha+i0} \frac{1}{\sqrt{p}} e^{pt} dp}_{\rightarrow 0}$$

$$\Rightarrow \psi(t) = \frac{-2}{\pi i} \int_{-i\infty}^{-i0} \frac{1}{\sqrt{p}} e^{pt} dp = \frac{-2}{\pi i} \int_{-i\infty}^{-i0} \frac{1}{\sqrt{p}} e^{pt} dp = \frac{-2}{\pi i} \int_0^{\infty} \frac{1}{\sqrt{p}} e^{pt} dp = \frac{1}{\pi i} \int_0^{\infty} \frac{1}{\sqrt{p}} e^{pt} dp$$

$$= \frac{2}{\pi} \int_0^{\infty} \frac{1}{\sqrt{p}} e^{-pt} dp$$

$$= \frac{2}{\pi} \cdot \frac{1}{2} \sqrt{\frac{\pi}{t}} = \sqrt{\frac{1}{\pi t}}$$

§7 数学物理定解方法

若性: 二阶线性偏微分方程

(a) Laplace 方程, Poisson 方程.

静电势分布

(b) 波动方程

波的传播

(c) 热传导方程.

热传导与扩散

(d) Maxwell 方程.

电磁场的变化

(e) Schrödinger 方程, Dirac 方程.

微观物质运动.

.....

pde: $u \equiv u(\vec{r}, t)$

$\vec{r} \equiv (x, y, z)$

$$\dots \frac{\partial^2 u}{\partial t^2} + \dots = \dots$$

空间 N 维 + 时间 = $(N+1)$ 维“时空”

二阶偏微分

$$\Delta u(x_0, x_1, \dots, x_N) = f(x_0, \dots, x_N)$$

物理场量 非齐次项

若 $f=0$ 则为齐次方程

$$\Delta = \sum_{i,j} a_{ij}(x_0, \dots, x_N) \frac{\partial^2}{\partial x_i \partial x_j} + \sum_i b_i(x_0, \dots, x_N) \frac{\partial}{\partial x_i} + c(x_0, \dots, x_N)$$

线性算子: $\hat{L}_1, \hat{L}_2$

$$\alpha(\hat{L}_1 + \hat{L}_2) = \alpha\hat{L}_1 + \alpha\hat{L}_2$$

$$(\alpha + \beta)\hat{L}_1 = \alpha\hat{L}_1 + \beta\hat{L}_1$$

$$(\alpha\hat{L}_1)\hat{L}_2 = \alpha(\hat{L}_1\hat{L}_2)$$

若为齐次方程

$$u_1, u_2 \text{ 为解 } \hat{L} u_1 = \hat{L} u_2 = 0$$

$$u = c_1 u_1 + c_2 u_2$$

$$\hat{L} u = c_1 \hat{L} u_1 + c_2 \hat{L} u_2$$

3D 欧氏空间

(a) $a_{11}=1, a_{12}=a_{21}=a^2, \text{其他}=0$

$$\hat{L} = \frac{\partial^2}{\partial x^2} - a^2 \nabla^2 \quad \text{双曲算子 (波动)}$$

波动 Eq: $U_{tt} - a^2 \nabla^2 U = f$

a - 波速

$$\begin{cases} t \rightarrow -t & \text{时间反演对称 (可逆)} \\ \vec{r} \rightarrow -\vec{r} & \text{空间对称} \end{cases}$$

(b) $b_{11}=1, b_{12}=b_{21}=b_{33}=-a^2, \text{其他}=0$

$$\hat{L} = \frac{\partial}{\partial t} - a^2 \nabla^2 \quad \text{抛物算子 (输运)}$$

$$U_t - a^2 \nabla^2 U = f$$

a - 输运系数

$$\begin{cases} \vec{r} \rightarrow -\vec{r} & \text{空间对称} \\ t \neq -t & \text{时间不可逆} \end{cases}$$

(c) $a_{11}=a_{22}=a_{33}=1, \text{其他}=0$

无耗 (即 t)
不需初始条件

$$\hat{L} = \nabla^2 \quad \text{Laplace 算子}$$

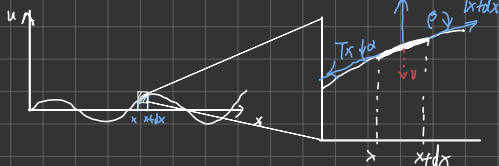
$$\nabla^2 U = f \quad \text{Poisson 方程 (椭圆算子) (稳态场)}$$

$$f=0 \rightarrow \nabla^2 U=0 \quad \text{Laplace 方程 (无源稳态场)}$$

Ex.

A. 波动方程

A. 均匀细弦 ($\gamma = \text{const.}$ 振幅微小)



x 向

$$T_x \cos \alpha - T_{x+dx} \cos \beta = 0$$

$$\downarrow d, \beta \rightarrow 0$$

$$T_x = T_{x+dx} \approx T$$

y 向

$$f(x,t) dx + T_{x+dx} \sin \beta - T_x \sin \alpha = \gamma dx \cdot U_{tt}$$

$$\downarrow d, \beta \rightarrow 0$$

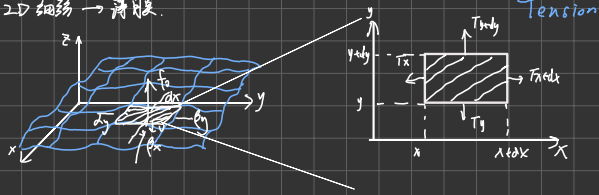
$$\begin{cases} \sin \alpha \approx \tan \alpha = \frac{\partial u}{\partial x} \Big|_x \\ \sin \beta \approx \tan \beta = \frac{\partial u}{\partial x} \Big|_{x+dx} \end{cases}$$

$$T \left(\frac{\partial u}{\partial x} \Big|_{x+dx} - \frac{\partial u}{\partial x} \Big|_x \right) + f(x,t) dx = \gamma dx \cdot U_{tt}$$

$$\stackrel{dx \rightarrow 0}{=} T \cdot \frac{\partial^2 u}{\partial x^2} dx + f(x,t) dx = \gamma dx \cdot U_{tt}$$

$$\Rightarrow U_{tt} - a^2 U_{xx} = f(x,t) \quad \begin{matrix} a^2 = T/\gamma \\ \gamma = \gamma/\lambda \end{matrix}$$

2D 细丝 → 薄膜



$$T_x \approx T_x dx \approx T_y \approx T_y dy = T$$

$$\underbrace{(T \sin \theta_x - T \sin \theta_y) dy}_{\text{①}} \approx T_{uxx} dx dy$$

$$\underbrace{(T \sin \theta_y - T \sin \theta_x) dx}_{\text{②}} \approx T_{yyx} dx dy$$

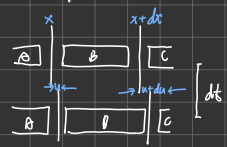
$$\text{②} + \text{①} + \int_0^t (x, y, t) dt = \sigma dx dy u_{tt}$$

$$\Rightarrow T_{uxx} + U_{yy} + f_0(x, y, t) = \sigma u_{tt}$$

$$u_{tt} - a^2 \nabla^2 u = f(x, y, t)$$

$$a = \sqrt{T/\sigma} \quad f = f_0/\sigma$$

A 棒能纵振



B 棒能纵振 $\frac{du}{dt} = u_t$

右边边界 $p(x, t)S, p(x+dx, t)S$

$$p \cdot S \cdot dx \cdot u_{tt} = [p(x+dx, t) - p(x, t)]S$$

$$\rho \frac{\partial u}{\partial t^2} = \frac{\partial p}{\partial x}$$

由 Hooke 定律 $p|_x = E \frac{\partial u}{\partial x}$ (杨氏模量)

$$\Rightarrow \frac{\partial u}{\partial t^2} - a^2 \frac{\partial^2 u}{\partial x^2} = 0$$

$$a = \sqrt{E/\rho}$$

3D 纵振:

$$\frac{\partial^2 u}{\partial t^2} - a^2 \nabla^2 u = 0$$

$$a = \sqrt{E/\rho}$$

§7.2 定解问题



定性

定量

存在
唯一
稳定

① 边界条件

② 初始条件

物理

历史

边界条件

自然

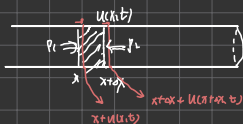
周期

阶跃 → 衍接

(可简凡, 可能失等点)

1) 波动问题.

eg 声音的传播.



物体运动 $\rightarrow$ p 改变 $\rightarrow$ p 传播

压强 $p = f(p)$ $p_0 = f(p_0)$

$$\begin{cases} p = f(p) = p_0 + \Delta p \\ p_0 = f(p_0) \end{cases}$$

$$\underbrace{f(p_0 + \Delta p)}_p = \underbrace{f(p_0)}_{p_0} + \underbrace{f'(p_0)}_{\Delta p}$$

$$p_1 \Delta x - p_2 \Delta x = p_0 \Delta x \cdot \frac{\partial}{\partial t} u(x,t)$$

$$1 \text{ bar} = 10^5 \text{ N/m}^2$$

$$1 = 20 \log_{10} \left(\frac{p}{p_0} \right)$$

$$\Delta p_1 - \Delta p_2 = p_0 \Delta x u_{tt}(x,t)$$

$$\left. \frac{d(p \Delta x)}{dx} \right|_{x=x} - \left. \frac{d(p \Delta x)}{dx} \right|_{x=x+\Delta x} = p_0 \Delta x u_{tt}(x,t) \quad p_{ref} = 2 \times 10^{-7} \text{ bar}$$

$$p_0 \Delta x \dot{S} = p_0 (\Delta x u(x,t+\Delta t) - u(x,t)) \dot{S}$$

$$\Rightarrow p_0 = p + p \frac{u(x,t+\Delta t) - u(x,t)}{\Delta x} = p + p \frac{\partial u}{\partial x}(x,t)$$

$$\Rightarrow \Delta p \Big|_{x=x} = -p \frac{\partial u}{\partial x}(x,t) = -p_0 \frac{\partial u}{\partial x}(x,t)$$

$$\Delta p \Big|_{x=x+\Delta x} = -p \frac{\partial u}{\partial x}(x+\Delta x,t) = -p_0 \frac{\partial u}{\partial x}(x+\Delta x,t)$$

$$\textcircled{1} \Rightarrow f'(p_0) \left[\frac{\partial u}{\partial x}(x+\Delta x,t) - \frac{\partial u}{\partial x}(x,t) \right] = p_0 \Delta x u_{tt}(x,t)$$

$$\Rightarrow f'(p_0) \frac{\partial}{\partial x} \left[\frac{\partial u}{\partial x} \right]_{x=x} - \frac{\partial}{\partial x} \left[\frac{\partial u}{\partial x} \right]_{x=x} = u_{tt}(x,t)$$

$$\frac{\partial^2 u}{\partial t^2} - f'(p_0) \frac{\partial^2 u}{\partial x^2} = 0$$

$$f'(p_0) = \frac{\partial p}{\partial \rho} \Big|_{p=p_0} = \gamma = c_s^2$$



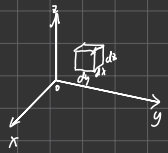
$$\frac{\partial^2 u}{\partial t^2} - \gamma \frac{\partial^2 u}{\partial x^2} = 0$$

2) 输运问题

扩散: $\vec{J} = -D \nabla u$
 扩散系数

扩散定律
 $u_t - D \Delta u = f(\vec{r}, t)$

ex. 中子 (Fission)
 $n + \text{铀} \rightarrow \text{碎片} + \beta n$



$$\begin{aligned}
 dN &= \Gamma_x dy dz dt + \Gamma_y dx dz dt + \Gamma_z dx dy dt \\
 &\quad - (\Gamma_{\text{back}} dy dz dt + \Gamma_{\text{yback}} dx dz dt + \Gamma_{\text{zback}} dx dy dt) \\
 &\quad + \rho u dx dy dz dt \\
 &= \frac{\partial u}{\partial t} dx dy dz dt
 \end{aligned}
 \Rightarrow
 \begin{aligned}
 \frac{\partial u}{\partial t} &= -\frac{\partial \Gamma}{\partial x} - \frac{\partial \Gamma}{\partial y} - \frac{\partial \Gamma}{\partial z} + \rho u \\
 &= D \frac{\partial^2 u}{\partial x^2} + D \frac{\partial^2 u}{\partial y^2} + D \frac{\partial^2 u}{\partial z^2} + \rho u \\
 &= \rho u + D \Delta u
 \end{aligned}$$

$$\frac{\partial u}{\partial t} - D \Delta u = \rho u$$

or

fission $\rho > 0$
 uniform $\rho = 0$ No origin / sink
 attenuation / decrease $\rho < 0$
 衰减.

$$\frac{\partial u}{\partial t} - \nabla \cdot (D \nabla u) = \rho u$$

$$\Rightarrow \frac{\partial u}{\partial t} - (\nabla D) \cdot (\nabla u) - D \Delta u = \rho u$$

3) 稳定场分布. ↘ 输运问题. 稳态状态 $u_t = 0$

$$\Delta u = -\frac{\rho u}{D}$$

$$\Delta u = -f(x, y, z, t)$$

$$\Delta u = -f(x, y, z)$$

$$\Delta u = 0$$

有源/汇

无源/汇

§7.2 定解条件.

一. 初始条件

1) 波包

$$u|_{t=0} = \psi(x)$$

初始位移

$$u_t|_{t=0} = \varphi(x)$$

初始速度

2) 稳态

$$u|_{t=0} = \phi(\vec{r})$$

初始分布

3) 无初始条件问题
 本征值问题
 共振振动

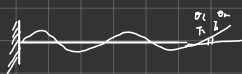
二、边界条件

① 波动

1) 第一类边界条件

$$u|_{x=0} = 0 \quad \text{固定边界条件}$$

$$u|_{x=L} = f(t) \quad \text{自由边界条件}$$



中间段

$$\begin{cases} T_1 \cos \theta_1 - T_2 \cos \theta_2 = \\ T_1 \sin \theta_1 - T_2 \sin \theta_2 = \rho a x u_{tt} \end{cases}$$

$$\frac{\partial u}{\partial t} = 0$$

边界

$$\begin{cases} T_1 \cos \theta_1 = T_2 \cos \theta_2 = T \\ T_1 \frac{\partial u}{\partial x} = \rho a x u_{tt} \Rightarrow T_1 \rightarrow 0 \end{cases}$$

$$T \frac{\partial u}{\partial x} = \rho a x u_{tt} \quad \text{即} \quad u_{tt} - \frac{T}{\rho} \frac{\partial^2 u}{\partial x^2} = 0$$

$$u_x|_{x=L} = 0$$

2) 第二类边界条件

$$u_x|_{x=L} = f(t)$$

3) 第三类边界条件



$$(u_x + h u)|_{x=b} = f(t)$$

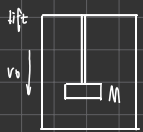
$$u_{tt} - \alpha^2 u_{xx} = 0$$

$$u|_{x=0} = 0$$

$$\left. \begin{matrix} F_1 \\ F_2 \end{matrix} \right|_x = \rho a x u_{tt}$$

$$\frac{\partial u}{\partial x} = \frac{1}{Y} \frac{F}{S} = \frac{1}{Y} \cdot \sigma$$

其他类边界条件



突然
停住

相似条件

$$u_{tt} - \frac{Y}{\rho} u_{xx} = 0$$

$$\frac{Mg}{S} = Y \frac{u_{max}}{L} \quad (u|_{x=L} = \frac{Mg}{SY} L)$$

初始条件

$$\begin{cases} u|_{t=0} = kx = \frac{Mg}{SY} x \\ u_t|_{t=0} = v_0 \end{cases}$$

边界条件

$$\begin{cases} u|_{x=0} = 0 \\ u_x|_{x=L} = \frac{Mg}{YS} - \frac{M}{YS} u_{tt}|_{x=L} \end{cases}$$

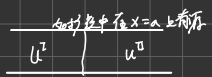


$$\begin{aligned} Mg - F &= M u_{tt}|_{x=L} \\ F &= Mg - M u_{tt}|_{x=L} = Y S u_x|_{x=L} \end{aligned}$$

注意事项

① 边界条件是整个时间范围内的边界条件。(某时刻可忽略不计)

② 内外边界效应若为同源，不应重复考虑。



③ 衔接条件

④

$$\begin{cases} u_t^I - D u_x^I = g \delta(x-a) \\ u_x^I - D u_x^{II} = 0 \\ u_x^{II} - D u_x^{III} = 0 \end{cases}$$

⑤ 注意在质点问题

⑥ 无边界问题

($x \rightarrow \infty$)

自然边界条件 $u|_{x \rightarrow \infty}$ 有限

上节导出的波动方程。除杆的横振动方程以外，每处边界上只起一个边界条件。以弦振动为例，弦*这个自变数而言，弦振动方程中出现二阶偏导数 u_{xx} ，是二阶微分方程。总共要求四个边界条件，即两端点各一个边界条件。杆的横振动方程中出现四阶偏导数 u_{xxxx} ，所以每个端点就要两个边界条件。例如，端点 $x=a$ 被固定(图 7-11a)，那么该端点的位移始终为零，而且杆在该处的斜率亦为零，即

$$u|_{x=a} = 0, \quad u_x|_{x=a} = 0. \quad (\text{固定端})$$

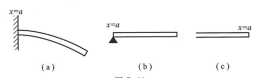


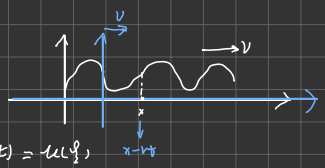
图 7-11

§7.3 行波法求解无限空间中的波动问题。

$$\begin{cases} u_{tt} - a^2 u_{xx} = 0, \quad -\infty < x < \infty \\ u|_{t=0} = \varphi(x) \\ u_t|_{t=0} = \psi(x) \end{cases}$$

$$u(x, t) = f(x - at) + g(x + at)$$

$$\begin{aligned} \frac{\partial u}{\partial t} &= \frac{\partial u}{\partial \xi} \frac{\partial \xi}{\partial t} = -a f'(\xi) + a g'(\eta) \\ \frac{\partial u}{\partial x} &= \frac{\partial u}{\partial \xi} \frac{\partial \xi}{\partial x} = f'(\xi) + g'(\eta) \\ v \frac{d^2 u}{d\xi^2} - a^2 \frac{d^2 u}{d\eta^2} &= 0 \\ u(x) &= \varphi(x) = f(x) + g(x) \\ -v u'(x) &= \psi(x) = -a f'(x) + a g'(x) \end{aligned}$$



$$\begin{aligned} \frac{\partial u}{\partial t} &= \frac{\partial}{\partial \xi} [u(\xi, \eta)] = v^2 u''(\xi) \\ \frac{\partial u}{\partial x} &= \frac{\partial}{\partial \xi} [u(\xi)] = u'(\xi) \\ v^2 &= a^2 \Rightarrow v = \pm a, \text{ 注意} \\ \frac{d^2 u}{d\xi^2} &= 0 \Rightarrow u = A\xi + B \xrightarrow{\xi \rightarrow \infty} A=0, u=B \text{ (常)} \\ u(x, t) &= f(x - at) + g(x + at) \end{aligned}$$

$$\begin{cases} u(x) = f(x) = f(x) + g(x) \\ -v(x) = \phi(x) = -\phi(f(x) + g(x)) \end{cases} \Rightarrow \begin{cases} f(x) + g(x) = f(x) \\ -f(x) + g(x) = -\frac{1}{a} \int_{-\infty}^x \psi(\eta) d\eta + C \end{cases} \Rightarrow \begin{cases} f(x) = \frac{1}{2} [\psi(x) - \frac{1}{a} \int_{-\infty}^x \psi(\eta) d\eta - C] \\ g(x) = \frac{1}{2} [\psi(x) + \frac{1}{a} \int_{-\infty}^x \psi(\eta) d\eta + C] \end{cases}$$

$$u(x, t) = \frac{1}{2} [\psi(x-at) + \psi(x+at)] + \frac{1}{2a} \int_{x-at}^{x+at} \psi(\eta) d\eta$$

这就是达朗贝尔公式

$$(\frac{1}{a^2} \frac{\partial^2}{\partial t^2} - \frac{\partial^2}{\partial x^2}) u(x, t) = 0$$

$$(\frac{1}{a^2} \frac{\partial}{\partial t} - \frac{\partial}{\partial x})(\frac{1}{a^2} \frac{\partial}{\partial t} + \frac{\partial}{\partial x}) u(x, t) = 0$$

$$\xi = x-at, \eta = x+at$$

$$\begin{cases} x = \frac{1}{2}(\eta + \xi) \\ t = \frac{1}{2a}(\eta - \xi) \end{cases} \Rightarrow \frac{\partial}{\partial \xi} \frac{\partial}{\partial \eta} u(\xi, \eta) = 0$$

$$\begin{aligned} \Rightarrow u(\xi, \eta) &= f(\xi) + g(\eta) \\ &= f(x-at) + g(x+at) \end{aligned}$$

$$\begin{aligned} \frac{\partial}{\partial \eta} &= \frac{\partial x}{\partial \eta} \frac{\partial}{\partial x} + \frac{\partial t}{\partial \eta} \frac{\partial}{\partial t} \\ &= \frac{1}{2} \frac{\partial}{\partial x} - \frac{1}{2a} \frac{\partial}{\partial t} \end{aligned}$$

$$\begin{aligned} \frac{\partial}{\partial \xi} &= \frac{\partial x}{\partial \xi} \frac{\partial}{\partial x} + \frac{\partial t}{\partial \xi} \frac{\partial}{\partial t} \\ &= \frac{1}{2} \frac{\partial}{\partial x} + \frac{1}{2a} \frac{\partial}{\partial t} \end{aligned}$$

$$\text{记 } \underline{\psi}(x) = \int_{-\infty}^x \psi(\eta) d\eta$$

$$u(x, t) = \frac{1}{2} [g(x+at) + f(x-at)] + \frac{1}{2a} [\underline{\psi}(x+at) - \underline{\psi}(x-at)]$$

半弦弦

$$\begin{cases} u_{tt} - a^2 u_{xx} = 0, & 0 \leq x < \infty \\ u|_{t=0} = g(x) & u|_{x=0} = 0 \\ u|_{t=\infty} = \phi(x) \end{cases}$$

$$\text{若 } u|_{x=0} = h(x)$$

$$h(x) \text{ 令 } u(x, t) = f(x) h(t) + \tilde{u}(x, t)$$

$$\text{又 } \begin{cases} f(0) = 1 \\ h'(t) f(0) - a^2 f''(t) h(t) = 0 \end{cases}$$

$$\text{Def } \Phi(x) = \begin{cases} g(x) & x > 0 \\ -g(x) & x < 0 \end{cases}$$

$$\underline{\psi}(x) = \begin{cases} \phi(x) & x > 0 \\ -\phi(x) & x < 0 \end{cases}$$



$$u(x, t) = -u(x, t)$$

$$\text{若 } \begin{cases} u|_{x=0} \Rightarrow \text{奇延拓} \\ u|_{x=\infty} \Rightarrow \text{偶延拓} \end{cases}$$

波动方程

$$u_{tt} - a^2 u_{xx} = \sin u$$

$$u(x, t) = u(\xi) = u(x-vt)$$

$$v^2 u_{\xi\xi} - a^2 u_{\xi\xi} = \sin u$$

$$\frac{d^2 u}{d\xi^2} = \frac{\sin u}{v^2 - a^2}$$

$$\frac{du}{d\xi} \frac{d\xi}{d\eta} = \frac{\sin u}{v^2 - a^2} \frac{d\eta}{d\xi}$$

$$\frac{1}{2} \frac{d}{d\xi} \left(\frac{du}{d\xi} \right)^2 = \frac{1}{v^2 - a^2} \frac{d}{d\xi} \cos u$$

$$\frac{du}{d\xi} = \sqrt{\frac{2 \cos u}{v^2 - a^2} + C_1}$$

$$d\xi = \frac{du}{\sqrt{\frac{2 \cos u}{v^2 - a^2} + C_1}}$$

$$\text{例 } u|_{x=0} = A \sin \omega t$$

$$\text{解法 } f(x) = \cos \theta x$$

$$-A a^2 \sin \omega t \cos \theta x + a^2 A \theta^2 \cos \theta x \sin \omega t = 0$$

$$-\omega + a^2 \theta^2 = 0 \Rightarrow \theta^2 = \frac{\omega^2}{a^2}$$

$$\text{则 } f(x) = \cos \frac{\omega}{a} x$$

$$u(x, t) = A \cos \frac{\omega}{a} x \sin \omega t + \tilde{u}(x, t)$$

$$\begin{cases} \tilde{u}_{tt} - a^2 \tilde{u}_{xx} = 0 \\ \tilde{u}|_{x=0} = 0 \\ \tilde{u}|_{t=0} = g(x) \\ \tilde{u}|_{t=\infty} = \phi(x) - \omega A \cos \frac{\omega}{a} x \end{cases}$$

$$\downarrow$$

$$\begin{aligned} \tilde{u}(x, t) &= \frac{1}{2} [\psi(x-at) + \phi(x+at)] \\ &\quad + \frac{1}{2a} \int_{x-at}^{x+at} \psi(\eta) d\eta - A \cos \frac{\omega}{a} x \sin \omega t \end{aligned}$$

§8. 分离变数法. 求解定解问题

本质 - Fourier 级数

$$\begin{cases} u_{tt} - a^2 u_{xx} = 0, & 0 \leq x \leq l \\ u|_{x=0} = 0 \\ u|_{x=l} = 0 \\ u|_{t=0} = \varphi(x) \\ u|_{t=\tau} = \psi(x) \end{cases}$$

$$u(x,t) = X(x)T(t)$$

$$X(x)T''(t) - a^2 X''(x)T(t) = 0$$

$$\Rightarrow \frac{T''(t)}{a^2 T(t)} = \frac{X''(x)}{X(x)} = -\lambda$$

(只能为常数)

$$\begin{cases} X''(x) + \lambda X(x) = 0 \\ T''(t) + a^2 \lambda T(t) = 0 \end{cases}$$

$$\Rightarrow \textcircled{1} \lambda > 0$$

$$X(x) = A \sin \sqrt{\lambda} x + B \cos \sqrt{\lambda} x$$

$$X(x) = A \sin \frac{n\pi}{l} x, \lambda = \frac{n^2 \pi^2}{l^2} \text{ 为本征值}$$

$$X(x) = A \sin \frac{n\pi}{l} x, \lambda = \frac{n^2 \pi^2}{l^2}$$

$$\textcircled{2} \lambda = 0$$

$$X(x) = A e^{\sqrt{\lambda} x} + B e^{-\sqrt{\lambda} x}$$

$$\begin{cases} A+B=0 \\ A e^{\sqrt{\lambda} l} + B e^{-\sqrt{\lambda} l} = 0 \end{cases} \Rightarrow \begin{cases} A=B=0 \Rightarrow X(x)=0 \\ \text{不成立, 舍去} \end{cases}$$

$$\textcircled{3} \lambda < 0$$

$$X(x) = A x + B$$

$$\begin{cases} B=0 \\ A l + B = 0 \end{cases} \Rightarrow \begin{cases} A=B=0 \Rightarrow X(x)=0 \\ \text{不成立, 舍去} \end{cases}$$

$$\text{解: } T''(t) + a^2 \lambda T(t) = 0$$

←

$$\text{得: } T_n(t) = C_n \sin \frac{a n \pi}{l} t + D_n \cos \frac{a n \pi}{l} t$$

↓

$$u_n(x,t) = (\tilde{C}_n \sin \frac{a n \pi}{l} t + \tilde{D}_n \cos \frac{a n \pi}{l} t) \cdot \sin \frac{n \pi}{l} x \quad \text{本征振动的驻波}$$

(n=1, 2, \dots)

$$\lambda = \frac{k l}{n} \quad (k=0, 1, 2, \dots, n) \Rightarrow \sin \frac{n \pi}{l} \lambda = 0$$

驻点 (驻点)

$$\text{半波长 } \frac{l}{n}, \text{ 波长 } \frac{2l}{n}$$

$$u(x,t) = \sum_{n=1}^{\infty} [\tilde{C}_n \sin \frac{a n \pi}{l} t + \tilde{D}_n \cos \frac{a n \pi}{l} t] \sin \frac{n \pi}{l} x$$

$$\text{代入初始条件} \begin{cases} u|_{t=0} = \varphi(x) \\ u|_{t=\tau} = \psi(x) \end{cases}$$

$$\text{求 } \tilde{C}_n, \tilde{D}_n \quad \sum_{n=1}^{\infty} \tilde{D}_n \sin \frac{n \pi}{l} x = \varphi(x) \quad \text{两边乘 } \sin \frac{m \pi}{l} x \quad \int_0^l \tilde{D}_n \sin \frac{n \pi}{l} x \cdot \sin \frac{m \pi}{l} x dx = \int_0^l \varphi(x) \sin \frac{m \pi}{l} x dx$$

$$\sum_{n=1}^{\infty} \tilde{C}_n \frac{a n \pi}{l} \sin \frac{n \pi}{l} x = \psi(x) \quad \text{两边乘 } \sin \frac{m \pi}{l} x \quad \int_0^l \tilde{C}_n \frac{a n \pi}{l} \sin \frac{n \pi}{l} x \cdot \sin \frac{m \pi}{l} x dx = \int_0^l \psi(x) \sin \frac{m \pi}{l} x dx$$

$$\parallel$$

$$\frac{\tilde{C}_n a n \pi}{2}$$

$$\Rightarrow \tilde{D}_n = \frac{2}{l} \int_0^l \varphi(x) \sin \frac{n \pi}{l} x dx$$

$$\Rightarrow \tilde{C}_n = \frac{2}{a n \pi} \int_0^l \psi(x) \sin \frac{n \pi}{l} x dx$$

$$\Rightarrow u(x,t) = \sum_{n=1}^{\infty} [\tilde{C}_n \sin \frac{a n \pi}{l} t + \tilde{D}_n \cos \frac{a n \pi}{l} t] \sin \frac{n \pi}{l} x$$

$$\begin{cases} \tilde{C}_n = \frac{2}{a n \pi} \int_0^l \psi(x) \sin \frac{n \pi}{l} x dx \\ \tilde{D}_n = \frac{2}{l} \int_0^l \varphi(x) \sin \frac{n \pi}{l} x dx \end{cases}$$

n次谐波最大振幅
逐渐衰减

$$u_{tt} - \alpha^2 u_{xx} = f(x, t)$$

⇒ 通解 + 特解

ii) $\begin{cases} u|_{x=0} = 0 \\ u|_{x=L} = 0 \end{cases}$ (第一类边界条件)

⇒ 通解为 $\cos$ 的展开形式 $u(x, t) = \sum_{n=1}^{\infty} T_n(t) \cos \frac{n\pi}{L} x$

if) $\begin{cases} u|_{x=0} = 0 \\ u|_{x=L} = 0 \end{cases}$ (第二类边界条件) $\begin{cases} u|_{x=L} = 0 \\ u|_{x=0} = 0 \end{cases}$

⇒ $u(x, t) = \sum_{n=0}^{\infty} T_n(t) \sin \lambda_n x$ $\Rightarrow u(x, t) = \sum_{n=0}^{\infty} T_n(t) \cos \lambda_n x$

$\lambda_n = \frac{(n+1)\pi}{2L}$
 $\Rightarrow u(x, t) = \sum_{n=0}^{\infty} T_n(t) \sin \frac{(n+1)\pi}{2L} x$

$\lambda_n = \frac{(2n+1)\pi}{2L}$
 $u(x, t) = \sum_{n=0}^{\infty} T_n(t) \cos \frac{(2n+1)\pi}{2L} x$

if) $\begin{cases} u|_{x=0} = 0 \\ (u + Hu_x)|_{x=L} = 0 \end{cases}$ (第三类边界条件)

⇒ $\begin{cases} X(0) = 0 \\ X(x) + HX'(x) = 0 \\ X''(x) + \lambda X(x) = 0 \end{cases} \Rightarrow \begin{cases} B = 0 \\ A \sin \sqrt{\lambda} L + H A \sqrt{\lambda} \cos \sqrt{\lambda} L = 0 \end{cases}$

$\sqrt{\lambda} L + \tan(\sqrt{\lambda} L + \varphi) = 0$
 $\sqrt{\lambda} L + \varphi = n\pi$
 $\lambda_n = \left(\frac{n\pi - \varphi}{L} \right)^2$
 $\tan \varphi = -\frac{H}{L}$ ($\varphi = \arctan \frac{H}{L}$)
 $\Rightarrow \lambda_n, \lambda_n = \frac{y_n^2}{L^2}$

$u(x, t) = \sum_{n=1}^{\infty} T_n(t) \sin \frac{y_n}{L} x$
 or $\sum_{n=1}^{\infty} T_n(t) \sin \frac{n\pi - \varphi}{L} x$
 非正弦

§ 8.2 傅里叶级数法可求解边界条件的非齐次方程

方法: 先求对应齐次方程

再满足齐次边界条件本征值问题 $\rightarrow \lambda_n, X_n(x)$

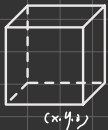
令 $u(x, t) = \sum_{n=1}^{\infty} T_n(t) X_n(x)$, $f(x, t) = \sum_{n=1}^{\infty} f_n(t) X_n(x)$

$u_{tt} - \alpha^2 u_{xx} = f(x, t)$

$\Rightarrow T_n''(t) - \alpha^2 \lambda_n T_n(t) = f_n(t)$

$$n + U^{235} \rightarrow \beta n + \text{碎片} + \gamma$$

$U(x, y, z, t)$
单位体积中子数



$$U_t - D \Delta U = \beta U \quad (\text{中子扩散})$$

$$\begin{cases} U|_{x=0} = 0, U|_{x=a} = 0 \\ U|_{y=0} = 0, U|_{y=b} = 0 \\ U|_{z=0} = 0, U|_{z=c} = 0 \end{cases}$$

临界体积

$$U_t = 0$$

↓

$$\Delta U + \frac{\beta}{D} U = 0$$

$$U(x, y, z) = X(x)Y(y)Z(z)$$

$$X''Y''Z + X''Y'Z + X'Y''Z + \frac{\beta}{D} XYZ = 0$$

$$\frac{X''}{X} + \frac{Y''}{Y} + \frac{Z''}{Z} + \frac{\beta}{D} = 0$$

↓

$$-X'' - Y'' - Z'' + \frac{\beta}{D} = 0$$

$$\begin{cases} X'' + \lambda_1 X = 0 \\ X(0) = X(a) = 0 \\ Y'' + \lambda_2 Y = 0 \\ Y(0) = Y(b) = 0 \\ Z'' + \lambda_3 Z = 0 \\ Z(0) = Z(c) = 0 \end{cases}$$

↓

$$\begin{cases} X = A_1 \sin \sqrt{\lambda_1} x + B_1 \cos \sqrt{\lambda_1} x \\ Y = A_2 \sin \sqrt{\lambda_2} y + B_2 \cos \sqrt{\lambda_2} y \\ Z = A_3 \sin \sqrt{\lambda_3} z + B_3 \cos \sqrt{\lambda_3} z \end{cases} \quad \begin{cases} B_1 = 0 \\ B_2 = 0 \\ B_3 = 0 \end{cases} \quad \begin{cases} \lambda_1 = \frac{n^2 \pi^2}{a^2} \\ \lambda_2 = \frac{m^2 \pi^2}{b^2} \\ \lambda_3 = \frac{k^2 \pi^2}{c^2} \end{cases}$$

$$\frac{\pi^2}{a^2} (n^2 + m^2 + k^2) = \frac{\beta}{D}$$

$$a^2 = \frac{D}{\beta} \pi^2 (n^2 + m^2 + k^2)$$

$$\begin{aligned} \text{临界体积 } V &= a_{min}^3 \quad (a_{min} = \sqrt{\frac{3D}{\beta}} \cdot \pi) \\ &= \left(\frac{3D}{\beta} \pi^2 \right)^{3/2} \end{aligned}$$

§8.2 非齐次边界问题的处理

$$\begin{cases} u_{tt} - \alpha^2 u_{xx} = f(x,t) \\ u|_{t=0} = \varphi(x) \\ u_t|_{t=0} = \psi(x) \\ u|_{x=0} = \mu(t) \\ u|_{x=L} = \nu(t) \end{cases}$$

$$\tilde{u}(x,t) = u(x,t) - \mu(t) + \frac{x}{L} [\mu(t) - \nu(t)]$$

$$\begin{cases} \tilde{u}|_{t=0} = u|_{t=0} - \mu(0) + \frac{x}{L} [\mu(0) - \nu(0)] = 0 \\ \tilde{u}|_{x=0} = u|_{x=0} - \mu(t) + \frac{x}{L} [\mu(t) - \nu(t)] = 0 \\ \tilde{u}|_{x=L} = u|_{x=L} - \mu(t) + \frac{x}{L} [\mu(t) - \nu(t)] = 0 \end{cases}$$

↓

$$\tilde{u}_{tt} - \alpha^2 \tilde{u}_{xx} = f(x,t) + \mu'(t) - \frac{x}{L} [\mu'(t) - \nu'(t)] - \alpha^2 \tilde{u}_{xx}$$

$$\begin{cases} \tilde{u}_{tt} - \alpha^2 \tilde{u}_{xx} = \tilde{f}(x,t) \\ \tilde{u}|_{t=0} = \tilde{\varphi}(x) \\ \tilde{u}_t|_{t=0} = \tilde{\psi}(x) \end{cases}$$

$$\text{if } \begin{cases} u|_{x=0} = \mu(t) \\ u|_{x=L} = \nu(t) \end{cases}$$

$$\tilde{u}(x,t) = u(x,t) - \mu(t) + \frac{x}{L} [\mu(t) - \nu(t)]$$

$$\text{if } \begin{cases} u|_{x=0} = \mu(t) \\ u|_{x=L} = \nu(t) \end{cases}$$

$$\tilde{u}(x,t) = u(x,t) - \mu(t) + \frac{x}{L} [\mu(t) - \nu(t)]$$

$$\text{if } \begin{cases} u|_{x=0} = \mu(t) \\ u|_{x=L} = \nu(t) \end{cases}$$

$$\tilde{u}(x,t) = u(x,t) - \mu(t) + \frac{x}{L} [\mu(t) - \nu(t)]$$

Ex: 输运问题 + 第三类边界条件



$$u_{tt} - \alpha^2 u_{xx} = 0, \quad \alpha^2 = \frac{k}{\rho c}$$

$$\begin{cases} u|_{x=0} = 0 \\ \left(\frac{\partial u}{\partial x} + \frac{h}{k} u \right) |_{x=L} = \frac{h}{k} \theta \\ u|_{t=0} = \varphi(x) \end{cases} \quad -k \frac{\partial u}{\partial x} |_{x=L-\theta} - h(u|_{x=L} - \theta) = \Delta u|_{x=L} \Rightarrow 0$$

$$\tilde{u} = u + A_0 + B_0 x$$

$$u|_{x=0} = \tilde{u}|_{x=0} + A_0 = 0 \Rightarrow A_0 = -u_0$$

$$\begin{aligned} \left(\frac{\partial u}{\partial x} + H u \right) |_{x=L} &= \left(\frac{\partial \tilde{u}}{\partial x} + B_0 + H \tilde{u} + H u_0 + H B_0 x \right) |_{x=L} \\ &= \left(\frac{\partial \tilde{u}}{\partial x} + H \tilde{u} \right) |_{x=L} + B_0 + H B_0 L + H u_0 \\ &= H \theta \end{aligned}$$

$$\Rightarrow B_0 = \frac{H \theta - H u_0}{1 + H L}$$

$$\text{求解: } \tilde{u}(x,t) = X(x)T(t)$$

$$\begin{cases} X'' + \lambda X = 0 \Rightarrow X = A_n \sin \sqrt{\lambda} x + B_n \cos \sqrt{\lambda} x \\ T' + \alpha^2 \lambda T = 0 \Rightarrow T = C_n e^{-\alpha^2 \lambda t} \end{cases}$$

$$\text{代入边界条件: } B_n = 0$$

$$A_n \sqrt{\lambda} \cos \sqrt{\lambda} L + A_n \sin \sqrt{\lambda} L = 0$$

$$\tan \sqrt{\lambda} L = -\frac{\sqrt{\lambda}}{H}$$

$$\text{eg } y = \frac{y}{H L}, \quad \lambda_n = \frac{y^2}{L^2}$$

$$\Rightarrow u = \tilde{u} + u_0 + \frac{H(u_0 - \theta)}{1 + H L} x$$

$$\tilde{u}_{tt} - \alpha^2 \tilde{u}_{xx} = 0$$

$$\begin{cases} \tilde{u}|_{t=0} = \varphi(x) - u_0 + \frac{H(u_0 - \theta)}{1 + H L} x \\ \tilde{u}|_{x=0} = 0 \end{cases}$$

$$\left(\frac{\partial \tilde{u}}{\partial x} + H \tilde{u} \right) |_{x=L} = 0$$

分离变量法

$$u(x,t) = D_n e^{-\alpha^2 \lambda t} \cdot \sin \sqrt{\lambda} x$$

代入初始条件

$$D_n = \frac{1}{\left(\frac{1}{L} \int_0^L \left[\varphi(x) - u_0 + \frac{H(u_0 - \theta)}{1 + H L} x \right] \sin \sqrt{\lambda} x dx \right)}$$

$$\tilde{u}(x,t) = \left(\frac{1}{L} \int_0^L \left[\varphi(x) - u_0 + \frac{H(u_0 - \theta)}{1 + H L} x \right] \sin \frac{y_n}{L} x dx \right) e^{-\alpha^2 \frac{y_n^2}{L^2} t} \cdot \sin \frac{y_n}{L} x$$

$$u(x,t) = \sum_{n=1}^{\infty} \left(\frac{1}{L} \int_0^L \left[\varphi(x) - u_0 + \frac{H(u_0 - \theta)}{1 + H L} x \right] \sin \frac{y_n}{L} x dx \right) e^{-\alpha^2 \frac{y_n^2}{L^2} t} \cdot \sin \frac{y_n}{L} x + u_0 + \frac{H(u_0 - \theta)}{1 + H L} x$$

一般问题

$$\begin{cases} u_{tt} - \alpha^2 u_{xx} = f(x, t) \\ u|_{x=0} = \mu(t) \\ u|_{x=L} = \nu(t) \\ u|_{t=0} = \varphi(x) \\ u_t|_{t=0} = \psi(x) \end{cases}$$

$$\text{令 } u(x, t) = \tilde{u}(x, t) + \mu(t) + \frac{x}{L} [\nu(t) - \mu(t)]$$

$$\tilde{u}_{tt} - \alpha^2 \tilde{u}_{xx} = \tilde{f}(x, t)$$

$$\begin{cases} \tilde{u}|_{x=0} = 0 \\ \tilde{u}|_{x=L} = 0 \\ \tilde{u}|_{t=0} = \tilde{\varphi}(x) \\ \tilde{u}_t|_{t=0} = \tilde{\psi}(x) \end{cases}$$

$$\tilde{u} = X \cdot T \quad \begin{cases} X'' + \lambda X = 0 \\ T'' + \alpha^2 \lambda T = 0 \end{cases}$$

$$u(x, t) = \sum_{n=1}^{\infty} T_n(t) \sin \frac{n\pi}{L} x$$

$$\sum_{n=1}^{\infty} \left[T_n''(t) + \alpha^2 \frac{n^2 \pi^2}{L^2} T_n(t) \right] \sin \frac{n\pi}{L} x = f(x, t)$$

$$\left[T_n''(t) + \alpha^2 \frac{n^2 \pi^2}{L^2} T_n(t) \right] = \frac{2}{L} \int_0^L f(x, t) \sin \frac{n\pi}{L} x dx = \bar{f}_n(t)$$

解 $py'' + qy' = a(x)$

齐次通解: y_1, y_2

求特解 $y = c_1 y_1 + c_2 y_2$

$$y' = c_1 y_1' + c_2 y_2'$$

$$(c_1' y_1 + c_2' y_2 = 0)$$

$$\Rightarrow \begin{cases} c_1 = \int \frac{a(x)}{y_1' y_2 - y_2' y_1} dx \\ c_2 = \int \frac{a(x)}{y_2' y_1 - y_1' y_2} dx \end{cases}$$

通解 $y = Ay_1 + By_2$
 $+ C_1(x)y_1 + C_2(x)y_2$

冲量原理

引例

$$u(x, t) \equiv \int_0^t v(x, t; \tau) d\tau$$

$$f(x, t) = \int_0^t f(x, \tau) \delta(t-\tau) d\tau$$

$$\frac{\partial u}{\partial t} = \int_0^t v_t(x, t; \tau) d\tau + \underbrace{v(x, t; t)}_{\text{11 deg 0}}$$

$$\frac{\partial^2 u}{\partial t^2} = \int_0^t v_{tt}(x, t; \tau) d\tau + \underbrace{v_t(x, t; t)}_{\text{11 deg 0}}$$

$$\Rightarrow \int_0^t v_{tt}(x, t; \tau) d\tau = \alpha^2 \int_0^t v_{xx}(x, t; \tau) d\tau$$

$$= \int_0^t v_{tt}(x, \tau) \delta(t-\tau) d\tau$$

$$\int_0^t v_{tt}(x, t; z) dz - a^2 \int_0^t v_{xx}(x, t; z) dz = \int_0^t f(x, z) \delta(t-z) dz$$

$$\Rightarrow \begin{cases} u|_{t=0} = 0 \\ u_t|_{t=0} = 0 \\ v|_{x=0} = 0 \\ v|_{x=L} = 0 \end{cases} \quad \text{over}$$

$$v_{tt}(x, t; z) - a^2 v_{xx}(x, t; z) = f(x, z) \delta(t-z)$$

$$\frac{1}{2} \quad t < z \text{ 时 } v = 0, \quad v_t = 0$$

$$\frac{1}{2} \quad t = z^+ \text{ 时}$$

$$\int_{t^-}^{t^+} v_{tt}(x, t; z) dt - a^2 \int_{t^-}^{t^+} v_{xx}(x, t; z) dt = \int_{t^-}^{t^+} f(x, z) \delta(t-z) dt = f(x, z)$$

$$\begin{array}{ccc} \text{1)} & & \text{1)} \\ v_t(x, t; z) \Big|_{t=t^-}^{t=t^+} & & 0 \\ \text{1)} & & \end{array}$$

$$v_t(x, t^+; z) - \underbrace{v_t(x, t^-; z)}_0$$

$$\Downarrow \\ v_t(x, t^+; z) = f(x, z)$$

$\Downarrow$

$$\begin{cases} v_{tt}(x, t; z) - a^2 v_{xx}(x, t; z) = 0 \\ v(x, z^+; z)|_{x=0} = 0 \\ v(x, z^+; z)|_{x=L} = 0 \\ v(x, t; z)|_{t=z^+} = 0 \\ v(x, t; z)|_{t=z^+} = f(x, z) \end{cases}$$

$$\begin{array}{l} \tilde{t} = t - z^+ \Rightarrow (t-z) \\ \xrightarrow{\quad\quad\quad} \begin{cases} v_{\tilde{t}\tilde{t}} - a^2 v_{xx} = 0 \\ v|_{\tilde{t}=0} = 0 \\ v|_{x=0} = 0 \\ v|_{x=L} = 0 \\ v|_{\tilde{t}=0} = f(x, z) \end{cases} \end{array}$$

3) 特殊常微分方程的级数解及本征值问题

Ex.1 方程导出

柱坐标: $\frac{1}{r \sin \theta} \frac{\partial}{\partial \varphi} \vec{e}_\varphi$

$\frac{\partial \vec{e}_r}{\partial r} = \frac{\partial \vec{e}_\theta}{\partial r} = \frac{\partial \vec{e}_\varphi}{\partial r} = 0$

$\frac{1}{r} \frac{\partial}{\partial \theta} \vec{e}_\theta$

$\frac{\partial \vec{e}_r}{\partial \theta} = -\vec{e}_\theta, \frac{\partial \vec{e}_\theta}{\partial \theta} = -\vec{e}_r, \frac{\partial \vec{e}_\varphi}{\partial \theta} = \frac{\partial (\vec{e}_r \times \vec{e}_\theta)}{\partial \theta} = \frac{\partial \vec{e}_r}{\partial \theta} \times \vec{e}_\theta + \frac{\partial \vec{e}_\theta}{\partial \theta} \times \vec{e}_r = 0$

$\frac{\partial}{\partial r} \vec{e}_r$

$\frac{\partial \vec{e}_r}{\partial \varphi} = \vec{e}_\varphi, \frac{\partial \vec{e}_\theta}{\partial \varphi} = \vec{e}_\varphi, \frac{\partial \vec{e}_\varphi}{\partial \varphi} = -\vec{e}_r$

$\vec{e}_r(r, \theta, \varphi) \quad \vec{e}_\theta(r, \theta, \varphi) \quad \vec{e}_\varphi(r, \theta, \varphi)$

$\begin{cases} x = r \sin \theta \\ y = r \cos \theta \end{cases}$

$\Delta = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \frac{\partial}{\partial r}) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta \frac{\partial}{\partial \theta}) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \varphi^2}$

$\Delta u = 0$

$u(r, \theta, \varphi) = R(r) Y(\theta, \varphi)$

$\Rightarrow Y(\theta, \varphi) \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 \frac{\partial}{\partial r} R(r)) + \frac{R(r)}{r^2 \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta \frac{\partial}{\partial \theta} Y(\theta, \varphi)) + \frac{R(r)}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \varphi^2} Y(\theta, \varphi) = 0$

$-\frac{1}{R(r)} \frac{\partial}{\partial r} (r^2 \frac{\partial}{\partial r} R(r)) = \frac{1}{Y(\theta, \varphi) \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta \frac{\partial}{\partial \theta} Y) + \frac{1}{Y \sin^2 \theta} \frac{\partial^2 Y}{\partial \varphi^2} = -\lambda$

$r^2 R'' + 2rR' - \lambda R = 0$

$\sin^2 \theta Y'' + Y' + \sin \theta \cos \theta Y' + \lambda \sin \theta Y = 0$

$Y = H(\theta) \Phi(\varphi)$

$\delta^2 \frac{H''}{H} + \frac{\delta H'}{H} + \lambda \delta = -\frac{\Phi''}{\Phi} = m^2$

$\begin{cases} r^2 R'' + 2rR' - \lambda R = 0 \xrightarrow{\lambda = l(l+1)} R(r) = C_1 r^l + C_2 \frac{1}{r^{l+1}} \\ \Phi'' + m^2 \Phi = 0 \Rightarrow \Phi(\varphi) = A_m \cos m\varphi + B_m \sin m\varphi \\ \sin^2 \theta H'' + \sin \theta \cos \theta H' + (\lambda \sin^2 \theta - m^2) H = 0 \end{cases}$

勒让德方程 ($m=0$)

$\sin \theta \frac{d}{d\theta} (\sin \theta \frac{dH}{d\theta}) + \lambda \sin^2 \theta H = 0$

柱坐标:

$\Delta u = \frac{1}{r} \frac{\partial}{\partial r} (r^2 \frac{\partial}{\partial r}) + \frac{1}{r^2} \frac{\partial^2}{\partial \varphi^2} = 0$

$u(r, \varphi, z) = R(r) \Phi(\varphi) Z(z)$

$\frac{1}{r} \Phi Z \frac{\partial}{\partial r} (r^2 \frac{\partial}{\partial r}) + \frac{1}{r^2} R Z \frac{\partial^2}{\partial \varphi^2} + R \Phi \frac{\partial^2}{\partial z^2} = 0$

$\frac{1}{R} \frac{1}{r} \frac{\partial}{\partial r} (r^2 \frac{\partial}{\partial r}) + \frac{1}{r^2} \frac{\Phi''}{\Phi} = -\frac{Z''}{Z} = -\lambda$

$\frac{r}{R} \frac{\partial}{\partial r} (r^2 \frac{\partial}{\partial r}) + \lambda r^2 = -\frac{\Phi''}{\Phi} = \lambda$

$$\Rightarrow \begin{cases} Z'' - \mu Z = 0 \\ Z' + \lambda Z = 0 \\ \rho^2 R'' + \rho R' + (\mu(\rho^2 - 1))A = 0 \end{cases}$$

$\mu > 0$. 实阶 Bessel 方程.
 $\mu < 0$. 虚阶 Bessel 方程.

波动.

$$u_{tt} - a^2 \Delta u = 0$$

$$u = V(\vec{r}) T(t)$$

$$V(\vec{r}) T''(t) - a^2 T(t) \Delta V(\vec{r}) = 0$$

$$\frac{T''(t)}{a^2 T(t)} = \frac{\Delta V(\vec{r})}{V(\vec{r})} = -\lambda$$

$$\Delta V(\vec{r}) + \lambda V(\vec{r}) = 0$$

亥姆霍兹方程 (波动方程)

输运

$$u_t - a^2 \Delta u = 0$$

$$u = V(\vec{r}) T(t)$$

$$V(\vec{r}) T'(t) - a^2 T(t) \Delta V(\vec{r}) = 0$$

$$\frac{T'(t)}{a^2 T(t)} = \frac{\Delta V(\vec{r})}{V(\vec{r})} = -\lambda$$

$$\Delta V(\vec{r}) + \lambda V(\vec{r}) = 0$$

亥姆霍兹方程

亥姆霍兹方程

→ 球坐标下, 分离变量.

$$\Delta V(\vec{r}) + k^2 V(\vec{r}) = 0$$

$$V(\vec{r}) = R(r) Y(\theta, \phi)$$

$$\Rightarrow \begin{cases} r^2 R'' + 2rR' - \ell(\ell+1)R + k^2 r^2 R = 0 & \text{球 Bessel 方程} \end{cases}$$

$$\sin\theta \frac{\partial}{\partial\theta} \sin\theta \frac{\partial Y}{\partial\theta} + \frac{\partial^2 Y}{\partial\phi^2} + \ell(\ell+1) Y \sin^2\theta = 0$$

$$\frac{1}{\sin\theta} \frac{\partial}{\partial\theta} \left(\sin\theta \frac{\partial Y}{\partial\theta} \right) + \left[\ell(\ell+1) - \frac{m^2}{\sin^2\theta} \right] Y(\theta) = 0$$

→ 柱坐标下

$$V(\vec{r}) = R(\rho) \Phi(\phi) Z(z)$$

修正 Bessel 方程

$m=0 \rightarrow$ 修正 Bessel 方程

$$\begin{cases} Z''(z) - \mu Z(z) = 0 \\ \Phi''(\phi) + m^2 \Phi(\phi) = 0 \end{cases}$$

$$\rho^2 R'' + \rho R' + [(\rho^2 + \mu)\rho^2 - m^2] R = 0$$

$$\rho^2 R'' + \rho R' + [(\rho^2 + \mu)\rho^2 - m^2] R = 0$$

$\mu > 0$ Bessel 方程.

$\mu < 0$ 虚阶 Bessel 方程.

§9.2 常点邻域上二阶常微分方程

$$y''(x) + p(x)y'(x) + q(x)y(x) = 0$$

$$\begin{cases} y'(x)|_{x=0} = C_1 \\ y(x)|_{x=0} = C_2 \end{cases}$$

↓ 变量

$$\frac{d^2 W(z)}{dz^2} + p(z) \frac{dW(z)}{dz} + q(z) W(z) = 0$$

$k=1, 2$ 在 $z=0$ 邻域上解析

$W(z)$ 在 $z=0$ 邻域上按幂级数展开

$$W(z) = \sum_{n=0}^{\infty} \alpha_n (z-2z_0)^n$$

$$y(x) = \sum_{n=0}^{\infty} \alpha_n (x-x_0)^n$$

$\lim_{n \rightarrow \infty} p(x), q(x)$ 有限

x_0 称为方程的常点，泰勒级数

若 $p(x), q(x)$ 其中一为无穷大，则 x_0 为奇点。 ← 正则：洛朗级数
一般

$$y'(x_0) + m^2 y(x_0) = 0$$

$$(p(x_0) = 0, q(x_0) = m^2)$$

($x=0$ 为方程常点)

$$y(x) = \sum_{n=0}^{\infty} \alpha_n x^n$$

$$\sum_{n=2}^{\infty} \alpha_n n(n-1)x^{n-2} + m^2 \sum_{n=0}^{\infty} \alpha_n x^n = 0$$

$$\text{令 } k=n-2, n=n+2$$

$$\text{有 } \alpha_{n+2}(n+2)(n+1)x^n$$

$$\text{令 } k=n$$

$$\text{有 } m^2 \alpha_n x^n$$

$$\left\{ \begin{aligned} & \alpha_{n+2}(n+2)(n+1) + m^2 \alpha_n = 0 \end{aligned} \right.$$

$$\alpha_{n+2} = -\frac{m^2}{(n+2)(n+1)} \alpha_n$$

$$\alpha_2 = -\frac{m^2}{2 \cdot 1} \alpha_0 = -\frac{m^2}{2} \alpha_0$$

$$\alpha_3 = -\frac{m^2}{3 \cdot 2} \alpha_1$$

$$\alpha_4 = -\frac{m^2}{4 \cdot 3} \alpha_2 = -\frac{m^4}{4!} \alpha_0$$

$$\alpha_5 = -\frac{m^4}{5!} \alpha_1$$

$$\alpha_6 = -\frac{m^6}{6!} \alpha_0$$

$$\begin{aligned} \Rightarrow \begin{cases} \alpha_{2k} = (-1)^k \frac{m^{2k}}{(2k)!} \alpha_0 \\ \alpha_{2k+1} = (-1)^k \frac{m^{2k}}{(2k+1)!} \alpha_1 \end{cases} \Rightarrow y(x) &= \sum_{k=0}^{\infty} \alpha_{2k} x^{2k} + \sum_{k=0}^{\infty} \alpha_{2k+1} x^{2k+1} \\ &= \alpha_0 \sum_{k=0}^{\infty} (-1)^k \frac{m^{2k}}{(2k)!} x^{2k} + \frac{\alpha_1}{m} \sum_{k=0}^{\infty} (-1)^k \frac{m^{2k+1}}{(2k+1)!} x^{2k+1} \\ &= \alpha_0 \cos mx + \frac{\alpha_1}{m} \sin mx \\ &\stackrel{\text{def}}{=} \alpha_0 \cos mx + \tilde{\alpha}_1 \sin mx \end{aligned}$$

$$\frac{1}{\sin \theta} \frac{d}{d\theta} \left(\sin \theta \frac{dH}{d\theta} \right) + \left[L(L+1) - \frac{m^2}{\sin^2 \theta} \right] H(\theta) = 0$$

$$\begin{aligned} X &\equiv \cos \theta \\ dX &= -\sin \theta d\theta \end{aligned} \quad \left. \begin{aligned} \sin^2 \theta &= 1 - \cos^2 \theta = 1 - X^2 \\ | -2X &< 1 \end{aligned} \right\}$$

$$-\frac{1}{\sin \theta} \frac{d}{d\theta} \left(\sin \theta \frac{dH}{d\theta} \right) + \left[L(L+1) - \frac{m^2}{1-X^2} \right] H = 0$$

$$\frac{d}{dx} \left((1-x^2) \frac{dH}{dx} \right) + \left[L(L+1) - \frac{m^2}{1-x^2} \right] \tilde{H}(x) = 0 \quad \text{综合勒让德方程}$$

Legendre

$$(1-x^2) \tilde{H}''(x) - 2x \tilde{H}'(x) + \left[L(L+1) - \frac{m^2}{1-x^2} \right] \tilde{H}(x) = 0$$

$$\begin{cases} P_{L,0} = \frac{-2x}{1-x^2} & x=0 \text{ 为奇点} \\ q(x) = \frac{L(L+1)}{1-x^2} - \frac{m^2}{(1-x^2)^2} & x=1, -1 \text{ 为奇点} \end{cases}$$

$$\tilde{H}(x) = \sum_{k=0}^{\infty} a_k x^k$$

$$\sum_{k=2}^{\infty} a_k k(k-1) x^{k-2} - \frac{2x}{1-x^2} \sum_{k=1}^{\infty} a_k k x^{k-1} + \left[\frac{L(L+1)}{1-x^2} - \frac{m^2}{(1-x^2)^2} \right] \sum_{k=0}^{\infty} a_k x^k = 0$$

$$\downarrow \quad \downarrow$$

$$\sum_{k=0}^{\infty} a_{k+2} (k+2)(k+1) x^k - \frac{2x}{1-x^2} \sum_{k=0}^{\infty} a_{k+1} (k+1) x^k + \left[\frac{L(L+1)}{1-x^2} - \frac{m^2}{(1-x^2)^2} \right] \sum_{k=0}^{\infty} a_k x^k = 0$$

$$\int_{-1}^1 (1-x^2) dx = 0$$

$$\sum_{k=0}^{\infty} a_{k+2} (k+2)(k+1) x^k - \sum_{k=2}^{\infty} a_k k(k-1) x^{k-2} - \sum_{k=1}^{\infty} 2 a_k k x^{k-1} + L(L+1) \sum_{k=0}^{\infty} a_k x^k = 0$$

$$a_{k+2} (k+2)(k+1) - a_k k(k-1) - 2 a_k k + L(L+1) a_k = 0$$

$$\Rightarrow a_{k+2} = \frac{k(k-1) - L(L+1)}{(k+2)(k+1)} a_k = \frac{(k-L)(k+L+1)}{(k+2)(k+1)} a_k$$

收敛半径 $R = \lim_{k \rightarrow \infty} \frac{(k+2)(k+1)}{(k-L)(k+L+1)} = 1$

$$\begin{cases} a_2 = \frac{-L(L+1)}{2 \times 1} a_0 \\ a_3 = \frac{(1-L)(2+L)}{3 \times 2} a_1 \\ a_4 = \frac{(2-L)(3+L)}{4 \times 3} a_2 = \frac{(2-L)(3-L)(4+L)}{4!} a_0 \\ a_5 = \frac{(3-L)(4+L)}{5 \times 4} a_3 = \frac{(3-L)(2-L)(4+L)(5+L)}{5!} a_1 \end{cases}$$

$$a_6 = \frac{(4-L)(5+L)}{6 \times 5} a_4 = \frac{(4-L)(3-L)(4-L)(5+L)(6+L)}{6!} a_0$$

$P_L(x)$ Legendre 多项式

$$\begin{cases} a_{2k} = \frac{(-1)^k (L+1) \dots (L-k+1)}{(2k)!} a_0 \\ a_{2k+1} = \frac{(-1)^k (L-1) \dots (L-k+1)}{(2k+1)!} a_1 \end{cases}$$

$$= \frac{(2k+L-1)!! (L-k+1) \dots (L-k+1)}{(2k)! (2k+L-1)!! (L-k+1) \dots (L-k+1)} = 1$$

人为偶 $\Rightarrow y_0(x)$ 为多项式 取 $a_1=0$

人为奇 $\Rightarrow y_1(x)$ 为多项式 取 $a_0=0$

人为整数 $\Rightarrow y_0(x), y_1(x)$ 为实数无穷级数

$$\tilde{H}(x) = \sum_{k=0}^{\infty} a_{2k} x^{2k} + \sum_{k=0}^{\infty} a_{2k+1} x^{2k+1}$$

$$= a_0 y_0(x) + a_1 y_1(x)$$

收敛

$$\text{对 } y_0: \frac{a_{2k+2}}{a_{2k}} = \frac{(2k+L-1)(2k+L)}{(2k+2)(2k+1)}$$

$$\lim_{k \rightarrow \infty} \frac{a_{2k+2}}{a_{2k}} = 1$$

收敛

正则奇点

$$p(x) = \sum_{k=1}^{\infty} p_k (x-x_0)^k$$

$\Rightarrow x=x_0$ 为 $y''(x) + p(x)y'(x) + q(x)y(x) = 0$ 的正则奇点

$$q(x) = \sum_{k=2}^{\infty} q_k (x-x_0)^k$$

作洛朗级数展开

(且非本性奇点)

故为 -1 或 -2 阶极点

$$\text{设 } y(x) = \sum_{k=0}^{\infty} a_k (x-x_0)^{k+s}$$

$$p(x) = \sum_{k=0}^{\infty} p_k (x-x_0)^{k+1}$$

$$y'(x) = \sum_{k=0}^{\infty} a_k (k+s) (x-x_0)^{k+s-1}$$

$$q(x) = \sum_{k=0}^{\infty} q_k (x-x_0)^{k+2}$$

$$y''(x) = \sum_{k=0}^{\infty} a_k (k+s)(k+s-1) (x-x_0)^{k+s-2}$$

$$x^2 y'' + x p(x) y' + x^2 q(x) y = 0$$

$\Downarrow$

$$\text{取首项 } (x-x_0)^{s-2} \rightarrow (x-x_0)^s$$

$$a_0 s(s-1) (x-x_0)^s + a_0 s p_0 (x-x_0)^s + a_0 q_0 (x-x_0)^s = 0$$

$$a_0 \neq 0$$

$$\Rightarrow s^2 + s(p_0 - 1) + q_0 = 0$$

$$s = \frac{1 \pm \sqrt{(p_0-1)^2 - 4q_0}}{2}$$

$$s_1 - s_2 = \sqrt{(p_0-1)^2 - 4q_0}$$

$$s_1 + s_2 = 1 - p_0$$

① 若 s_1, s_2 非整数

Legendre 方程

$$y_1(x) = \sum_{k=0}^{\infty} a_k (x-x_0)^{k+s_1}$$

$$r^2 R'(r) + 2r R''(r) - l(l+1) R(r) = 0$$

$$y_2(x) = \sum_{k=0}^{\infty} b_k (x-x_0)^{k+s_2}$$

$$R'' + \frac{2}{r} R' - \frac{l(l+1)}{r^2} R = 0, \quad x=0 \text{ 为正则奇点}$$

② 若 s_1, s_2 为整数

$$p_0 = 2, \quad q_0 = -l(l+1)$$

y_1, y_2 可能非独立

$$\begin{cases} s_1 = l \\ s_2 = -(l+1) \end{cases} \Rightarrow \begin{cases} y_1(r) = \sum_{k=0}^{\infty} a_k r^{k+l} \\ y_2(r) = \sum_{k=0}^{\infty} b_k r^{k-l-1} \end{cases}$$

$\Rightarrow$ 洛朗级数

$$y_2 = A y_1 + \ln(x-x_0) + \sum_{k=0}^{\infty} b_k (x-x_0)^{k+s_2}$$

若 $A=0$, 则 y_1, y_2 是 0 等价

$$\begin{cases} r^2 y_1'' + 2r y_1' - l(l+1) y_1 = 0 \\ r^2 y_2'' + 2r y_2' - l(l+1) y_2 = 0 \end{cases}$$

$$a_k (k+l)(k+l-1) + 2(k+l) a_k - l(l+1) a_k = 0$$

$$a_k [k^2 + (2l+1)k] = 0 \Rightarrow a_k = 0$$

$$b_k (k-l-1)(k-l-2) + 2(k-l-1) b_k - l(l+1) b_k = 0$$

$$b_k [k^2 - (2l+1)k] = 0 \Rightarrow b_k = 0$$

$\Downarrow$

$$R(r) = a_0 r^l + b_0 r^{-l-1}$$

若相展至非正则奇点

$\Downarrow$

则不波函数到第二个解

L 为整数 $\iff$ 包络轴.

$$\rho^2 R''(\rho) + \rho R'(\rho) + (\mu^2 - m^2) R(\rho) = 0$$

$$\text{令 } x = \sqrt{\mu} \rho$$

$$\Rightarrow x^2 R''(x) + x R'(x) + (x^2 - m^2) R(x) = 0$$

$$x^2 R''(x) + \frac{1}{x} R'(x) + (1 - \frac{m^2}{x^2}) R(x) = 0$$

$$p_1 = 1 \quad \begin{cases} q_2 = -m^2 \\ q_0 = 1 \end{cases} \Rightarrow \begin{cases} s_1 = \frac{1 - p_1 + \sqrt{(p_1 - 1)^2 - 4q_2}}{2} = m \\ s_2 = -m \end{cases}$$

1) m 为整数

$$\begin{cases} y_1(x) = \sum_{k=0}^{\infty} a_k x^{k+m} \\ y_2(x) = \sum_{k=0}^{\infty} b_k x^{k-m} \end{cases}$$

$$x^2 y_1'' + x y_1' + (x^2 - m^2) y_1 = 0$$

$$\begin{cases} (m+1)(m) a_1 + (m+1) a_1 - m^2 a_1 = 0, & (1-2m) a_1 = 0 \Rightarrow a_1 = a_2 = \dots = a_{m+1} = 0 \\ (m+2)(m+1) a_2 + (m+2) a_2 + a_0 - m^2 a_2 = 0, & a_2 = \frac{-a_0}{4(m+1)} \\ (m+k)(m+k-1) a_k + k a_k + a_{k-2} - m^2 a_k = 0, & a_k = \frac{-a_{k-2}}{k(m+k)} \end{cases}$$

$$a_{2k} = \frac{-a_{2k-2}}{2k(2m+2k)}$$

$$a_4 = \frac{-a_0}{4 \cdot 2(m+4)} = \frac{(-1)^2 a_0}{4 \cdot 2(2m+4)(2m+2)}$$

$$a_6 = \frac{(-1)^3 a_0}{6 \cdot 4 \cdot 2(2m+6)(2m+4)(2m+2)}$$

$$\Rightarrow a_{2k} = \frac{(-1)^k a_0}{2^{2k} k! (m+k) \dots (m+1)} = \frac{(-1)^k \Gamma(m+1)}{2^{2k} k! \Gamma(m+k+1)} \cdot a_0$$

$$R(x) = C_1 J_m(x) + C_2 J_{-m}(x)$$

$$R(\rho) = C_1 J_m(\sqrt{\mu} \rho) + C_2 J_{-m}(\sqrt{\mu} \rho)$$

(x_m 为 $J_m(x)$ 的零点)

$$R(\rho) = 0 \Rightarrow J_m(\sqrt{\mu} \rho) = 0, \quad \mu_n = \left(\frac{x_n}{\rho_0}\right)^2 \Rightarrow J_m(\sqrt{\mu} \rho) = J_m(x_n \frac{\rho}{\rho_0})$$

$$\lim_{\rho \rightarrow 0} R(\rho) \text{ 有限} \Rightarrow C_2 = 0$$

$$\begin{aligned} y_1(x) &= \sum_{k=0}^{\infty} \frac{(-1)^k 2^{2k} \Gamma(m+1)}{k! \Gamma(m+k+1)} a_0 x^{2k+m} \\ &= \tilde{a}_0 \sum_{k=0}^{\infty} \frac{(-1)^k}{k! \Gamma(m+k+1)} \left(\frac{x}{2}\right)^{2k+m} \end{aligned}$$

$$J_m(x) = \sum_{k=0}^{\infty} \frac{(-1)^k}{k! \Gamma(m+k+1)} \left(\frac{x}{2}\right)^{2k+m}$$

m 为 Bessel 函数

$$y_2(x) = \tilde{b}_0 J_{-m}(x) = \tilde{b}_0 \sum_{k=0}^{\infty} \frac{(-1)^k}{k! \Gamma(-m+k+1)} \left(\frac{x}{2}\right)^{2k-m}$$

2) m 为整数.

$$J_{-m} \sim \sum_{k=0}^{\infty} \frac{(-1)^k}{k! \Gamma(-m+k+1)} \left(\frac{x}{2}\right)^{2k-m}$$

$$J_{-1}(x) = \frac{1}{\Gamma(0)} \left(\frac{x}{2}\right)^{-1} + \frac{(-1)^1}{1! \Gamma(1)} \left(\frac{x}{2}\right)^1 + \frac{(-1)^2}{2! \Gamma(2)} \left(\frac{x}{2}\right)^2$$

$\xrightarrow{\rightarrow 0}$

$$J_{-1}(x) = \frac{1}{\Gamma(1)} \left(\frac{x}{2}\right)^1 + \frac{(-1)^1}{1! \Gamma(2)} \left(\frac{x}{2}\right)^2$$

递推关系

$$\Rightarrow y_1 = J_m(x)$$

$$y_2 = A J_m(x) \ln x + \sum_{k=0}^{\infty} b_k x^{k-m}$$

$$y_2' = A J_m'(x) \ln x + A \frac{1}{x} J_m(x) + \sum_{k=0}^{\infty} (k-m) b_k x^{k-m-1}$$

$$y_2'' = A J_m''(x) \ln x + A J_m''(x) \left(\frac{1}{x}\right) + A \left(\frac{1}{x^2}\right) J_m(x) + \sum_{k=0}^{\infty} (k-m)(k-m-1) b_k x^{k-m-2}$$

$$\text{代入 } x^2 y_2'' + x y_2' + (x^2 - m^2) y_2 = 0$$

$$x^2 y_2'' = A x^2 J_m''(x) \ln x + 2 A x J_m'(x) - A J_m(x) + \sum_{k=0}^{\infty} (k-m)(k-m-1) b_k x^{k-m}$$

$$x y_2' = A x J_m'(x) \ln x + A J_m(x) + \sum_{k=0}^{\infty} (k-m) b_k x^{k-m}$$

$$(x^2 - m^2) y_2 = A x^2 J_m''(x) \ln x - \sum_{k=0}^{\infty} m^2 b_k x^{k-m} + \sum_{k=0}^{\infty} b_k x^{k-m+2}$$

$$\Rightarrow \text{对 } x^m: \quad 0 \cdot b_0 = 0 \quad b_0 \text{ 任意}$$

$$\text{对 } x^{-(m+1)}: \quad (1-m) b_1 = 0, \quad b_1 = 0$$

$$\text{对 } x^m: \quad A \frac{m}{m!} \frac{1}{x^m} + 0 \cdot b_{2m} + b_{2m-2} = 0$$

$$A = -(m-1)! \cdot 2^m b_{m-2}$$

$$\Rightarrow \text{Def } y_2 \text{ as } N_m(x)$$

$$N_m(x) \xrightarrow{x \rightarrow 0} \text{发散}$$

$$\begin{cases} y_1'' + p y_1' + q y_1 = 0 & \textcircled{1} \\ y_2'' + p y_2' + q y_2 = 0 & \textcircled{2} \end{cases}$$

$$0 \times y_2 - 0 \times y_1 = y_2 y_1' - y_1 y_2' + p(y_1' y_2 - y_2' y_1)$$

$$\text{Def } \Delta(x) = y_1' y_2 - y_2' y_1$$

$$\frac{d\Delta}{dx} = y_1'' y_2 - y_2'' y_1$$

$$\Rightarrow \frac{d\Delta}{dx} + p\Delta(x) = 0$$

$$\frac{d\Delta(x)}{\Delta(x)} = -p(x) dx$$

$$\ln \Delta(x) = -\int p(x) dx$$

$$\Delta(x) = \Delta e^{-\int p(x) dx} \quad *$$

$$\frac{d}{dx} \left(\frac{y_2}{y_1} \right) = \frac{y_2' y_1 - y_1' y_2}{y_1^2} = -\frac{\Delta(x)}{y_1^2}$$

$$\frac{y_2}{y_1} = -\int \frac{\Delta(x)}{y_1^2} dx = -\int \frac{\Delta_0 e^{-\int p(x) dx}}{y_1^2} dx$$

$$y_2 = -y_1 \int \frac{\Delta_0 e^{-\int p(x) dx}}{y_1^2} dx$$

$$p(x) = p_1(x-x_0)^{-1} + p_0(x-x_0)^0 + p_2(x-x_0)^2 + \dots$$

$$S_1 - S_2 = h$$

$$\int p(x) dx = p_1 \ln(x-x_0) + T_1$$

$$S_1 + S_2 = 1 - p_1$$

$$y_2 = -y_1 \int \frac{\Delta_0 e^{-\int p(x) dx}}{y_1^2} dx = -y_1 \int \frac{\Delta_0 e^{-T_1} (x-x_0)^{-p_1}}{y_1^2} dx = -y_1 \int \frac{T_2 (x-x_0)^{-p_1}}{y_1^2} dx = -y_1 \int (x-x_0)^{-p_1-2S_1} T_3(x) dx$$

$$= -y_1 \int (x-x_0)^{-h-1} T_3(x) dx$$

if h is integer

$$\text{LHS} = A y_1(x) \ln(x-x_0) + (x-x_0)^{S_1} (x-x_0)^{-h} T_{ky}$$

$$= A y_1(x) \ln(x-x_0) + \sum_{k=0}^{\infty} b_k (x-x_0)^{k+S_1}$$

非正则奇点

$$y''(x) + p(x)y'(x) + q(x)y(x) = 0$$

$$y(x) = \int_{x_0}^{\infty} a(x-x_0)^{r_1} dx$$

$$\underbrace{(x-x_0)^{s-2} + (x-x_0)^{s-1} (x-x_0)^{p_{min}} + (x-x_0)^s (x-x_0)^{q_{min}}}_{\text{可能无解}}$$

故用幂级数展开来求解。

§9.4 Sturm-Liouville 本征值问题。

$$\frac{d}{dx} [k(x) \frac{dy}{dx}] - q(x)y + \lambda p(x)y = 0$$

$$k(x)y''(x) + k'(x)y'(x) - q(x)y(x) + \lambda p(x)y(x) = 0$$

$$\begin{cases} k(x) = e^{\int a(x) dx} \\ q(x) = -b(x) e^{\int a(x) dx} \\ p(x) = c(x) e^{\int a(x) dx} \end{cases}$$

1. 第二类/第二类/第二类边界条件
(包括自然条件)

系统构成 S-L 本征值问题。

$$y|_{x=a} = 0 \quad / \quad y'|_{x=b} = 0 \quad / \quad y + Hy'|_{x=a} = 0$$

例 ① $a=0, b=L, k(x)=\text{const}, q(x)=0, p(x)=\text{const}$

$$y''(x) + \lambda y(x) = 0$$

$$\begin{cases} y|_{x=a} = 0 \\ y|_{x=b} = 0 \end{cases} \Rightarrow y = \sin \frac{n\pi}{L} x$$

$$\begin{cases} y|_{x=a} = 0 \\ y'|_{x=b} = 0 \end{cases} \Rightarrow y = \sin \frac{(n+\frac{1}{2})\pi}{L} x$$

① $a = -1, b = 1, k(x) = 1-x^2, q(x) = 0, p(x) = 1$

$$\frac{d}{dx}[(1-x^2) \frac{dy}{dx}] + \lambda y = 0 \quad \begin{cases} y(1) \\ y(-1) \end{cases} \text{有限}$$

Legendre 方程

if $q(x) = \frac{m^2}{1-x^2}$

$$(1-x^2)y'' - 2xy' + \left[1 - \frac{m^2}{1-x^2}\right]y(x) = 0$$

综合 Legendre 方程.

性质:

① 若 $k(x), p(x)$ 连续, or 在 $a, x=b$ 处有一阶极点, 则存在无穷多本征值 λ_n

对应无穷多个本征函数.

$$(\lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_n \leq \dots)$$

② 所有本征值 $\lambda_n \geq 0$

③ 对不同本征值 λ_1, λ_2 对应的本征函数 y_1, y_2 在 (a,b) 上带权重 $p(x)$ 正交.

$$\int_a^b y_1(x) y_2(x) p(x) dx = 0, \lambda_1 \neq \lambda_2$$

$$\begin{cases} \frac{d}{dx} \left[p(x) \frac{dy}{dx} \right] - q(x) y + \lambda y = 0 \quad ① \\ \frac{d}{dx} \left[p(x) \frac{dy}{dx} \right] - q(x) y + \lambda y = 0 \quad ② \end{cases}$$

$$\frac{d}{dx} [p(x) y_1 \frac{dy_2}{dx} - p(x) y_2 \frac{dy_1}{dx}] = 0$$

or $y_1 y_2 - y_2 y_1$ 表达式

$$\int_a^b \underbrace{y_1 \frac{d}{dx} [p(x) \frac{dy_2}{dx}]}_{=0} - \underbrace{y_2 \frac{d}{dx} [p(x) \frac{dy_1}{dx}]}_{=0} + (\lambda_1 - \lambda_2) \underbrace{\int_a^b y_1 y_2 p(x) dx}_{=0} = 0$$

即 $\int_a^b \frac{d}{dx} [p(x) (y_1 y_2' - y_2 y_1')] dx$ 由分部积分法为 0

④ 完备性

$$f(x) = \sum_{n=1}^{\infty} c_n y_n(x)$$

$$c_n = \frac{\int_a^b f(x) y_n(x) p(x) dx}{\int_a^b y_n^2(x) p(x) dx}$$

复数形式

正交性:
$$\int_a^b y_n(x) y_m^*(x) \rho(x) dx$$

$$= 0$$

归一化

$$f_n = \frac{1}{\sqrt{N_n}} \int_a^b y_n(x) y_n^*(x) \rho(x) dx$$

$$\Phi'' + \lambda \Phi = 0$$

$$\Phi_m = e^{im\varphi}$$

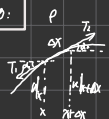
$$\int_0^{2\pi} \Phi_n(\varphi) \Phi_m^*(\varphi) d\varphi = \int_0^{2\pi} e^{im\varphi} e^{-in\varphi} d\varphi = 2\pi \delta_{m,n}$$

$$f(\varphi) = \sum_{-\infty}^{\infty} f_n e^{in\varphi}, \quad f_n = \frac{1}{2\pi} \int_0^{2\pi} f(\varphi) e^{-in\varphi} d\varphi$$

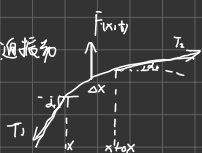
一、波动方程

弦振动:

1) 无受阻



1) 受迫振动



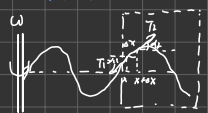
2) 阻尼振动

$$f(x,t) = \frac{F(x,t)}{\rho} = -\frac{1}{\rho} \frac{\partial u}{\partial t}$$

阻尼函数

$$\frac{\partial u}{\partial t} - \alpha \frac{\partial^2 u}{\partial x^2} + \lambda \frac{\partial u}{\partial t} = 0$$

弦具有加速度



初始条件

$$u|_{t=0} - \alpha^2 u|_{x=0} = 0$$

$$\begin{cases} u|_{t=0} = \varphi(x) \\ u|_{t=0} = \psi(x) \end{cases}$$

→ 初始位移

→ 初始速度

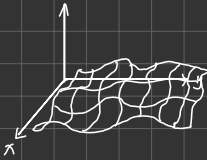
$$u = \begin{cases} \frac{F}{T} \cdot \frac{x-x_0}{L} & 0 \leq x < x_0 \\ \frac{F}{T} \cdot \frac{x_0}{L} (1-x) & x_0 < x < L \end{cases}$$

$$T \frac{\partial^2 u}{\partial x^2} + \frac{\partial u}{\partial t} = F$$

$$y = \frac{F}{T} \cdot \frac{x(x-x_0)}{L}$$

$$u|_t = \begin{cases} 0 & |x-x_0| > 0 \\ \frac{1}{T} I \delta(x-x_0) & |x-x_0| < 0 \end{cases}$$

平面振动



$$(F|_{x+\Delta x} - F|_x) dy \approx 0$$

$$(F|_{y+\Delta y} - F|_y) dx \approx 0$$

$$F|_{x+\Delta x} dy|_{x+\Delta x} - F|_x dy|_x + F|_{y+\Delta y} dx|_{y+\Delta y} - F|_y dx|_y = \rho dx dy u_{tt}$$

$$F_x u_{xx} + F_y u_{yy} = \rho u_{tt}$$

$$F_x \approx F_y$$

$$\Rightarrow u_{tt} - \alpha^2 \Delta u = 0, \quad \alpha^2 = \frac{F}{\rho} \equiv f$$

杆纵振动

1) 无受阻

$$F|_{x+\Delta x} - F|_x = \gamma S u|_{x+\Delta x} - \gamma S u|_x = \rho S dx u_{tt}$$

$$u_{tt} - \alpha^2 u_{xx} = 0$$

$$\alpha^2 = \frac{Y}{\rho}$$

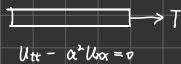


(2) 受迫振动

边界条件

均匀受迫

非典型边界条件



考虑边界条件

$$F|_{x=l} = T$$

$$T = YS u_x|_{x=l}$$

$$u_x|_{x=l} = \frac{T}{YS}$$

$$\begin{cases} u|_{x=0} = 0 \\ u|_{x=l} = \frac{T}{YS} \end{cases}$$

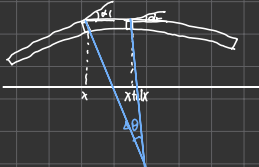
波速 $\frac{d^2 u}{dt^2} = \frac{M}{YI} = u_{xx}$, $M = YI u_{xx}$

简谐 $M|_x - M|_{x+dx} - T dx = 0$, $T = -\frac{\partial M}{\partial x} = -YI u_{xx}$

$$T|_x - T|_{x+dx} = \rho dx \frac{d^2 u}{dt^2}$$

$$YI u_{xxx} = \rho u_{tt}, \quad u_{tt} - \frac{YI}{\rho} u_{xxx} = 0$$

杆横振动



$$\tan \alpha \approx \alpha = u_x \quad (\alpha \rightarrow 0)$$

$$|AO| = |O_2 - O_1| = \sqrt{(\Delta x)^2 + (\Delta u)^2} = \frac{[1 + (u_x)^2]^{1/2} \Delta x}{R}$$

$$\Rightarrow \frac{dO}{dx} = [1 + (u_x)^2]^{1/2} / R = \frac{dL}{dx}$$

$$\tan \alpha = u_x$$

$$\frac{\partial \tan \alpha}{\partial x} = u_{xx} = \frac{\partial}{\partial x} \left(\frac{\sin \alpha}{\cos \alpha} \right) = (1 + \tan^2 \alpha) \frac{\partial \alpha}{\partial x} = [1 + (u_x)^2] \cdot \frac{[1 + (u_x)^2]^{1/2}}{R}$$

$$R = \frac{[1 + (u_x)^2]^{1/2}}{u_{xx}}, \quad \frac{dO}{dx} = \frac{dL}{dx} = \frac{u_{xx}}{1 + (u_x)^2}$$

$$YI \left[\frac{(R+y) d\theta - dx}{dx} \right] = YI \left[\frac{(R+y) \frac{dx}{R} - dx}{dx} \right] = YI \frac{y}{R} = F$$

$$J = b dy$$

$$F = \frac{YI b}{R} dy$$

对A点给: $F_y = \frac{YI b}{R} y dy$

$$\int_{x_0}^x u = \frac{Y}{R} \int b y dy = \frac{Y}{R} I_c = \frac{YI_c u_{xx}}{[1 + (u_x)^2]^{1/2}} \xrightarrow{u_x \rightarrow 0} YI_c u_{xx}$$

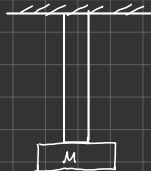
$$M|_{x+dx} - M|_x + F dx = 0$$

$$F = -\frac{\partial M}{\partial x} = -YI_c u_{xxx}$$

$$F|_x - F|_{x+dx} = \rho dx \frac{d^2 u}{dt^2}$$

$$YI_c u_{xxxx} = \rho u_{tt}$$

$$u_{tt} - \frac{YI_c}{\rho} u_{xxxx} = 0$$



$$u_{tt} - \alpha^2 u_{xxx} = 0$$

$$\begin{cases} u|_{t=0} = 0 \\ u_t|_{t=0} = 0 \\ u|_{x=0} = 0 \\ (u_{tt} - g + \frac{YI_c}{M} u_x)|_{x=l} = 0 \end{cases}$$

$$\frac{u_t}{u} = \frac{dx}{dt}$$

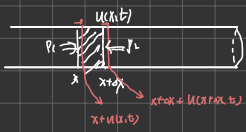
$$u g - F|_{x=l} = M u_{tt}|_{x=l}$$

$$F|_{x=l} - F|_{x+dx} = YI_c (u_x|_{x=l} - u_x|_{x+l+dx}) = \rho dx u_{tt}$$

$$dx \rightarrow 0, \quad F|_{x=l} = M g - u_{tt}|_{x=l} = YI_c u_x|_{x=l}$$

$$(u_{tt} - g + \frac{YI_c}{M} u_x)|_{x=l} = 0$$

声音的传播



介质运动 $\rightarrow$ p 改变 $\rightarrow p$ 波动

压强 $p = f(p)$ $p_0 = f(p_0)$

$$\begin{cases} p = f(\psi) = p_0 + \Delta p \\ p_0 = f(p_0) \end{cases}$$

$$p_1 S - p_2 S = p_0 S \cdot \Delta x \cdot \frac{\partial}{\partial t} u(x,t)$$

$$1 \text{ bar} = 10^5 \text{ N/m}^2$$

$$\Delta p_1 - \Delta p_2 = p_0 \Delta x u_{tt}(x,t)$$

$$1 = 20 \log_{10} \left(\frac{\Delta p}{p_{ref}} \right)$$

$$p_{ref} = 2 \times 10^{-10} \text{ bar}$$

$$\underbrace{f(p_0 + \Delta p)}_p = \underbrace{f(p_0)}_{p_0} + \underbrace{f'(p_0) \Delta p}_{\Delta p}$$

$$\left. \frac{d}{dt} (p_0 \Delta x) \right|_{x=x} - \left. \frac{d}{dt} (p_0 \Delta x) \right|_{x=x+\Delta x} = p_0 \Delta x u_{tt}(x,t) \quad p_{ref} = 2 \times 10^{-10} \text{ bar}$$

$$p_0 \Delta x S = p(x + u(x,t) \Delta t) - p(x,t) S$$

$$\Rightarrow p_0 = p + p \frac{U(x,t) \frac{\partial}{\partial x} p(x,t)}{\Delta x} = p + p \frac{\partial}{\partial x} u(x,t)$$

$$\Rightarrow \Delta p|_{x=x} = -p \frac{\partial u}{\partial x}(x,t) = -p_0 \frac{\partial u}{\partial x}(x,t)$$

$$\Delta p|_{x=x+\Delta x} = -p \frac{\partial u}{\partial x}(x+\Delta x,t) = -p_0 \frac{\partial u}{\partial x}(x+\Delta x,t)$$

$$\Rightarrow \frac{d}{dt} \left[p_0 \left(\frac{\partial u}{\partial x}(x+\Delta x,t) - \frac{\partial u}{\partial x}(x,t) \right) \right] = p_0 \Delta x u_{tt}(x,t)$$

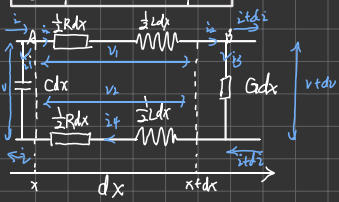
$$\Rightarrow f'(p_0) \frac{\partial}{\partial x} \left[\frac{\partial u}{\partial x}(x+\Delta x,t) - \frac{\partial u}{\partial x}(x,t) \right] = u_{tt}(x,t)$$

$$\frac{\partial^2 u}{\partial t^2} - f'(p_0) \frac{\partial^2 u}{\partial x^2} = 0$$

$$f'(p_0) = \left. \frac{\partial p}{\partial \rho} \right|_{p=p_0} = \gamma = C_s^2$$

$$\frac{\partial^2 u}{\partial t^2} - \gamma \frac{\partial^2 u}{\partial x^2} = 0$$

电传输或电报方程



① at A: $i = i_1 + i_2$

at B: $i_2 = i_3 + i_4 = i_3 + i_5 + d i + i_6$

$$i_1 + i_3 + d i = 0$$

$$i = \frac{d \phi}{d t} = C dx \frac{\partial v}{\partial t}, \quad i_3 = G dx (v + dv) = G dx v$$

$$d i_2 = -C dx \frac{\partial v}{\partial t} - G dx v, \quad i_2 = i - C dx \frac{\partial v}{\partial t}$$

$$\frac{\partial i}{\partial x} = -C \frac{\partial v}{\partial t} - G v \quad \square$$

② From A to A (C.W.)

$$v_1 + v + dv + v_2 - v = 0$$

$$v_1 + v_2 + dv = 0$$

$$v_1 = i_2 \frac{1}{2} R dx + \frac{1}{2} L dx \frac{\partial i_2}{\partial t}, \quad v_2 = i_1 \frac{1}{2} R dx + \frac{1}{2} L dx \frac{\partial i_1}{\partial t} = \frac{1}{2} R dx + \frac{1}{2} L dx \frac{\partial i}{\partial t}$$

$$i R dx + L dx \frac{\partial i}{\partial t} + dv = 0 \quad \frac{\partial v}{\partial x} = -i R - L \frac{\partial i}{\partial t} \quad \Delta$$

$$\square \begin{cases} \frac{\partial i}{\partial x} = -C \frac{\partial v}{\partial t} - G v \\ \Delta \begin{cases} \frac{\partial v}{\partial x} = -L \frac{\partial i}{\partial t} - R i \end{cases} \end{cases}$$

$$\begin{cases} \frac{\partial^2 v}{\partial x^2} = -C \frac{\partial v}{\partial t} - Gv & ① \\ \frac{\partial v}{\partial x} = -L \frac{\partial^2 v}{\partial t^2} - Ri & ② \end{cases}$$

$$\begin{cases} \frac{\partial^2 v}{\partial x^2} = -C \frac{\partial v}{\partial t} - Gv \\ \frac{\partial v}{\partial x} = -L \frac{\partial^2 v}{\partial t^2} - Ri \end{cases} \Rightarrow \frac{\partial^2 v}{\partial x^2} = CL \frac{\partial^2 v}{\partial t^2} + CR \frac{\partial v}{\partial t} - Gv = CL \frac{\partial^2 v}{\partial t^2} + (CR + GL) \frac{\partial v}{\partial t} + GRv$$

$$\begin{cases} \frac{\partial v}{\partial x} = -L \frac{\partial^2 v}{\partial t^2} - Ri \\ \frac{\partial v}{\partial x} = -C \frac{\partial v}{\partial t} - Gv \end{cases} \Rightarrow \frac{\partial^2 v}{\partial x^2} = CL \frac{\partial^2 v}{\partial t^2} + GL \frac{\partial v}{\partial t} - Ri = CL \frac{\partial^2 v}{\partial t^2} + (GL + RC) \frac{\partial v}{\partial t} + GRv$$

↓

$$u_{tt} - \alpha^2 u_{xx} + 2b u_t + cu = 0$$

$$\text{忽略 } G, R \Rightarrow u_{tt} - \alpha^2 u_{xx} = 0 \quad (u = i\omega v) \quad \alpha = \frac{1}{\sqrt{CL}}$$

二. 输运方程.

热传导方程.



$$\text{有热源: } u_t - \alpha^2 u_{xx} = f(x, t)$$

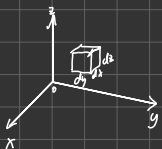
$$Q_{in} = -kS \Delta t \frac{\partial u}{\partial x} \Big|_x \quad Q_{out} = -kS \Delta t \frac{\partial u}{\partial x} \Big|_{x+\Delta x}$$

$$Q_{in} - Q_{out} = c \rho S \Delta x \Delta u$$

$$k \frac{\partial u}{\partial x} = c \rho \frac{\partial u}{\partial t} \Rightarrow u_t - \frac{k}{c\rho} u_{xx} = 0$$

$$u_t - \alpha^2 u_{xx} = 0, \quad \alpha^2 = \frac{k}{c\rho}$$

扩散方程



$$n + \Delta n \rightarrow \alpha n + \beta n$$

$$dN = \Gamma_x dy dz dt + \Gamma_y dx dz dt + \Gamma_z dx dy dt$$

$$-(\Gamma_{yx} dy dz dt + \Gamma_{xy} dx dz dt + \Gamma_{zx} dx dy dt)$$

$$+ \beta u dx dy dz dt$$

$$= \frac{\partial u}{\partial t} dx dy dz dt$$

$$\frac{\partial u}{\partial t} - D \Delta u = \beta u$$

or

$$\frac{\partial u}{\partial t} - \nabla \cdot (D \nabla u) = \beta u$$

$$\Rightarrow \frac{\partial u}{\partial t} - (\nabla D) \cdot (\nabla u) - D \Delta u = \beta u$$

$$\begin{aligned} \frac{\partial u}{\partial t} &= -\frac{\partial \Gamma}{\partial x} - \frac{\partial \Gamma}{\partial y} - \frac{\partial \Gamma}{\partial z} + \beta u \\ &= D \frac{\partial^2 u}{\partial x^2} + D \frac{\partial^2 u}{\partial y^2} + D \frac{\partial^2 u}{\partial z^2} + \beta u \\ &= \beta u + D \Delta u \end{aligned}$$

Fission $\beta > 0$

uniform $\beta = 0$

attenuation decrease $\beta < 0$

衰减.

No origin / sink

三. 稳定场分布.

$$\text{Maxwell Equation} \begin{cases} \vec{\nabla} \cdot \vec{D} = \rho \\ \vec{\nabla} \cdot \vec{B} = 0 \\ \vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \\ \vec{\nabla} \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t} \end{cases}$$

$$\text{Material Equation} \begin{cases} \vec{D} = \epsilon_0 \vec{E} \\ \vec{B} = \mu_0 \vec{H} \\ \vec{J} = \sigma \vec{E} \end{cases}$$

$$\textcircled{1} \quad \nabla \times (\nabla \times \vec{E}) = \nabla(\nabla \cdot \vec{E}) - \nabla^2 \vec{E}$$

$$\text{I.} \quad \nabla \times (\nabla \times \vec{E}) = \nabla \times \left(-\frac{\partial \vec{B}}{\partial t} \right) = -\frac{\partial}{\partial t} (\nabla \times \vec{B}) = -\mu_0 \frac{\partial}{\partial t} (\nabla \times \vec{H}) = -\mu_0 \frac{\partial}{\partial t} \left[\vec{J} + \frac{\partial \vec{D}}{\partial t} \right]$$

$$\mu_0 \sigma \frac{\partial \vec{E}}{\partial t} - \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2}$$

$$\text{II.} \quad \nabla(\nabla \cdot \vec{E}) = \frac{1}{\epsilon_0} \nabla(\nabla \cdot \vec{D}) = \frac{1}{\epsilon_0} \nabla \rho \stackrel{\text{assume}}{\underset{\rho=0}{=}} 0$$

$$\text{III.} \quad \nabla^2 \vec{E} = \Delta \vec{E}$$

$$\Rightarrow \mu_0 \epsilon_0 \frac{\partial^2 \vec{E}}{\partial t^2} + \mu_0 \sigma \frac{\partial \vec{E}}{\partial t} = \Delta \vec{E}$$

$$\textcircled{2} \quad \nabla \times (\nabla \times \vec{H}) = \nabla(\nabla \cdot \vec{H}) - \nabla^2 \vec{H}$$

$$\text{I.} \quad \nabla \times (\nabla \times \vec{H}) = \nabla \times \left(\vec{J} + \frac{\partial \vec{D}}{\partial t} \right) = \nabla \times \vec{J} + \epsilon_0 \frac{\partial}{\partial t} \nabla \times \vec{E} = (\nabla \times \epsilon_0 \frac{\partial}{\partial t} (\nabla \times \vec{E}))$$

$$= -\mu_0 \sigma \frac{\partial \vec{H}}{\partial t} - \mu_0 \epsilon_0 \frac{\partial^2 \vec{H}}{\partial t^2}$$

$$\text{II.} \quad \nabla(\nabla \cdot \vec{H}) = \frac{1}{\mu_0} \nabla(\nabla \cdot \vec{B}) = 0$$

$$\text{III.} \quad \nabla^2 \vec{H} = \Delta \vec{H}$$

$$\Rightarrow \mu_0 \epsilon_0 \frac{\partial^2 \vec{H}}{\partial t^2} + \mu_0 \sigma \frac{\partial \vec{H}}{\partial t} = \Delta \vec{H}$$

When $\sigma = 0$ (电磁波损耗为0)

$$\text{then} \quad \begin{cases} \frac{\partial^2 \vec{E}}{\partial t^2} - c^2 \nabla^2 \vec{E} = 0 \\ \frac{\partial^2 \vec{H}}{\partial t^2} - c^2 \nabla^2 \vec{H} = 0 \end{cases}$$

